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Product Manual

# LD25 Series

**ST9402115A**  
**ST920217A**

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One gigabyte, or GB, equals one billion bytes when referring to hard drive capacity. Accessible capacity may vary depending on operating environment and formatting. Quantitative usage examples for various applications are for illustrative purposes. Actual quantities will vary based on various factors, including file size, file format, features and application software. Seagate reserves the right to change, without notice, product offerings or specifications.

# Contents

<b>1.0</b>	<b>Introduction</b>	<b>1</b>
<b>2.0</b>	<b>Drive specifications</b>	<b>3</b>
2.1	Specification summary	3
2.2	Formatted capacity	5
2.3	Default logical geometry	5
2.4	Physical organization	5
2.5	Recording and interface technology	5
2.6	Physical characteristics	6
2.7	Seek time	6
2.8	Time to ready	6
2.9	Power specifications	7
2.9.1	Power consumption	7
2.9.2	Conducted noise	8
2.9.3	Voltage tolerance	8
2.9.4	Power-management modes	9
2.10	Environmental specifications	10
2.10.1	Ambient temperature	10
2.10.2	Temperature gradient	10
2.10.3	Humidity	10
2.10.4	Altitude	10
2.10.5	Shock	11
2.10.6	Vibration	11
2.11	Acoustics	12
2.12	Electromagnetic immunity	12
2.13	Reliability	13
2.14	Agency certification	13
2.14.1	Safety certification	13
2.14.2	Electromagnetic compatibility	13
2.14.3	FCC verification	14
2.15	Environmental protection	15
2.15.1	European Union Restriction of Hazardous Substances (RoHS)	15
2.16	Corrosive environment	15
<b>3.0</b>	<b>Configuring and mounting the drive</b>	<b>17</b>
3.1	Handling and static discharge precautions	17
3.2	Jumper settings	17
3.2.1	Master/slave configuration	17
3.2.2	Cable-select option	18
3.3	Drive mounting	19
<b>4.0</b>	<b>ATA interface</b>	<b>21</b>
4.1	ATA interface signals and connector pins	21
4.1.1	Supported ATA commands	22
4.1.2	Identify Device command	25
4.1.3	Set Features command	28
<b>5.0</b>	<b>Seagate Technology support services</b>	<b>29</b>



# List of Figures

Figure 1. Jumper settings ..... 17  
Figure 2. Mounting dimensions—top, side and end view ..... 19



## 1.0 Introduction

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This manual describes the functional, mechanical and interface specifications for the following Seagate® LD25 Series drives:

- ST9402115A
- ST920217A

Seagate LD25 Series drives comprise a new product category of 2.5-inch form factor drives designed for non-notebook PC applications such as:

- Consumer electronics (gaming, small PVRs/DVRs)
- Ultra-small desktop PCs
- Internet appliances

LD25 Series drives are quieter, lighter and use less power than 3.5-inch drives. They are ideal for applications requiring the form and fit of a notebook drive but without some of the design specifications required by notebook drives such as high shock tolerance, high performance, and power management. LD25 Series drives are not presently suited for notebook applications or environments with high operating temperatures.

These drives provide the following key features:

- 5,400-RPM spindle speed
- 2-Mbyte buffer
- High instantaneous (burst) data transfer rates (up to 100 Mbytes per second) using Ultra DMA mode 5.
- Tunneling Magnetoresistive (TMR) recording heads.
- State-of-the-art cache and on-the-fly error-correction algorithms.
- Full-track multiple-sector transfer capability without local processor intervention.
- Quiet operation.
- 500 Gs nonoperating shock.
- SeaTools™ diagnostic software performs a drive self-test that eliminates unnecessary drive returns.
- The 3D Defense System™, which includes Drive Defense, Data Defense, and Diagnostic Defense, offers the industry's most comprehensive protection for disc drives.
- Support for S.M.A.R.T. drive monitoring and reporting.
- Support for Read Multiple and Write Multiple commands.





## 2.0 Drive specifications

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Unless otherwise noted, all specifications are measured under ambient conditions, at 25°C, and nominal power. For convenience, the phrases *the drive* and *this drive* are used throughout this manual to indicate ST9402115A and ST920217A model drives.

### 2.1 Specification summary

The specifications listed in this table are for quick reference. For details on specification measurement or definition, see the appropriate section of this manual.

**Table 1: Specifications**

Drive specification	ST9402115A	ST920217A
Formatted Gbytes (512 bytes/sector)*	40	20
Guaranteed sectors	82,443,600	41,021,800
Bytes per sector	512	
Default sectors per track	63	
Default read/write heads	16	
Default cylinders	16,383	
Physical read/write heads	2	1
Discs	1	1
Recording density, BPI (bits/inch typical)	675,900	
Track density, TPI (tracks/inch typical)	114,000	
Areal density (Gbits/inch <sup>2</sup> max)	81	
Spindle speed (RPM)	5,400	
Internal data transfer rate OD (Mbytes/sec max)	57.6	
I/O data-transfer rate (Mbytes/sec max)	100	
ATA data-transfer modes supported	PIO modes 0–4 Multiword DMA modes 0–2 Ultra DMA modes 0–5	
Cache buffer (Mbytes)	2	
Height	9.5 +/-0.2 mm (0.374 +/-0.008 inches)	
Width	69.85 +/-0.25 mm (2.750 +/-0.010 inches)	
Length	100.2 +/-0.25 mm (3.945 +/-0.010 inches)	
Weight (typical)	100 grams (0.22 lb)	
Average latency (msec)	5.6	
Power-on to ready (sec typical)	4.0	
Standby to ready (sec typical)	3.0	
Track-to-track seek time (msec typical)	1.0 (read), 1.5 (write)	
Average seek, read (msec typical)	<16	
Average seek, write (msec typical)	<16	

**Table 1: Specifications**

<b>Drive specification</b>	<b>ST9402115A</b>	<b>ST920217A</b>
Full-stroke seek (msec)	22 (typical); 24 (max)	
Startup current 5V (amps typical) (max = +/- 10%)	1.0	
Seek power, random r/w, desktop usage (watts, typical)	2.3	
Idle mode (watts, typical)	2.0	
Standby and sleep modes (watts, typical)	<0.5	
Voltage tolerance (including noise)	5V ± 5%	
Ambient temperature	5° to 55°C (operating), -40° to 70°C (nonoperating)	
Temperature gradient (°C per hour max, noncondensing)	20°C (operating) 30°C (nonoperating)	
Relative humidity (noncondensing)	8% to 90% (operating) 5% to 95% (nonoperating)	
Relative humidity gradient	30% per hour max	
Wet bulb temperature (°C max)	30°C (operating) 40°C (nonoperating)	
Altitude, operating	-304.8 m to 3,048 m (-1000 ft to 10,000 ft)	
Altitude, nonoperating (below mean sea level, max)	-304.8 m to 12,192 m (-1,000 ft to 40,000 ft)	
Shock, operating (Gs max at 2 msec)	100	
Shock, nonoperating (Gs max at 2 msec)	500	
Shock, nonoperating (Gs max at 1 msec)	350	
Shock, nonoperating (Gs max at 0.5 msec)	200	
Vibration, operating	0.5 G (22–350 Hz) 0.25 G (351–500 Hz)	
Vibration, nonoperating	5 Gs (0 to peak, 22–350 Hz) 1.0 G (351–500 Hz)	
Drive acoustics, sound power (bels), 2 disc		
Idle**	2.4 (typical)	
Seek	2.7 (typical)	
Nonrecoverable read errors	1 per 10 <sup>14</sup> bits read	
Annualized Failure Rate (AFR)	<1.0%, Desktop and gaming use	
Service life	5 Years	
Warranty	To determine the warranty for a specific drive, use a web browser to access the following web page: <a href="http://www.seagate.com/support/service/">www.seagate.com/support/service/</a> From this page, click on the "Verify Your Warranty" link. You will be asked to provide the drive serial number, model number (or part number) and country of purchase. The system will display the warranty information for your drive.	
Load/Unload (L/UL) cycles		
Controlled L/UL cycles (40°C, 50% relative humidity)	50,000	
Emergency L/UL cycles (40°C, 50% relative humidity)	20,000	

\*One Gbyte equals one billion bytes when referring to hard drive capacity. Accessible capacity may vary depending on operating environment and formatting.

\*\*During periods of drive idle, some offline activity may occur, according to the S.M.A.R.T. specification, which may increase acoustic and power to operational levels.

## 2.2 Formatted capacity

Model	Formatted capacity*	Guaranteed sectors	Bytes per sector
ST9402115A	40 Gbytes	82,443,600	512
ST920217A	20 Gbytes	41,021,800	512

\*One Gbyte equals one billion bytes when referring to hard drive capacity. Accessible capacity may vary depending on operating environment and formatting.

## 2.3 Default logical geometry

Cylinders	Read/write heads	Sectors per track
16,383	16	63

### LBA mode

When addressing these drives in LBA mode, all blocks (sectors) are consecutively numbered from 0 to  $n-1$ , where  $n$  is the number of guaranteed sectors as defined above.

## 2.4 Physical organization

Model	Read/write heads	Number of discs
ST9402115A	2	1
ST920217A	1	1

## 2.5 Recording and interface technology

Interface	Parallel ATA
Recording density BPI (bits/inch typical)	675,900
Track density TPI (tracks/inch typical)	114,000
Areal density (Gbits/inch <sup>2</sup> max)	81
Spindle speed (RPM) ( $\pm 0.2\%$ )	5,400
Internal data-transfer rate OD (Mbytes/sec max)	57.6
I/O data-transfer rate (Mbytes/sec max)	100 (Ultra DMA mode 5)
Interleave	1:1
Cache buffer	2 Mbytes (2,048 kbytes)

## 2.6 Physical characteristics

Height	(mm) (inches)	9.5 +/-0.2 0.374 +/-0.008
Width	(mm) (inches)	69.85 +/-0.25 2.750 +/-0.010
Length	(mm) (inches)	100.2 +/-1.45 3.945 +/-0.057
Typical weight	(grams) (pounds)	100 0.22

## 2.7 Seek time

Seek measurements are taken with nominal power at 25°C ambient temperature. All times are measured using drive diagnostics. The specifications below are defined as follows:

- Track-to-track seek time is an average of all possible single-track seeks in both directions.
- Average seek time is a true statistical random average of at least 5,000 measurements of seeks between random tracks, less overhead.

Typical seek times (msec)	Read	Write
Track-to-track	<2	<2
Average	<16	<16
Full-stroke	<24	<24
Average latency	5.6	5.6

**Note.** These drives are designed to consistently meet the seek times represented in this manual. Physical seeks, regardless of mode (such as track-to-track and average), are expected to meet or exceed the noted values. However, due to the manner in which these drives are formatted, benchmark tests that include command overhead or measure logical seeks may produce results that vary from these specifications.

## 2.8 Time to ready

Time to ready	Typical	Max @ 25°C
Power-on to Ready (sec)	4.0	8.0
Standby to Ready (sec)	3.0	8.0

## 2.9 Power specifications

The drive receives DC power (+5V) through the 4-pin power connector.

### 2.9.1 Power consumption

Power requirements for the drives are listed in the table on page 7. Typical power measurements are based on an average of drives tested, under nominal conditions, at 25°C ambient temperature.

- **Spinup power**

Spinup power is measured from the time of power-on to the time that the drive spindle reaches operating speed.

- **Seek mode**

During seek mode, the read/write actuator arm moves toward a specific position on the disc surface and does not execute a read or write operation. Servo electronics are active. Seek mode power is measured based on three random seek operations every 100 msecs. This mode is not typical.

- **Read/write power and current**

Read/write power is measured with the heads on track, based on three 63 sector read or write operations every 100 msecs.

- **Idle mode power\***

Idle mode power is measured with the drive up to speed, with servo electronics active and with the heads in a random track location.

- **Standby mode**

During Standby mode, the drive accepts commands, but the drive is not spinning, and the servo and read/write electronics are in power-down model

**Table 2: DC power**

Power dissipation	+5V average (25° C)
Spinup (typical)	1.0 Amp
Seek, random r/w, desktop usage	2.3 Watts
Idle*	2.0 Watts
Standby and sleep modes	<0.5 watts

\*During periods of drive idle, some offline activity may occur according to the S.M.A.R.T. specification, which may increase acoustic and power to operational levels.

### 2.9.1.1 Typical current profile

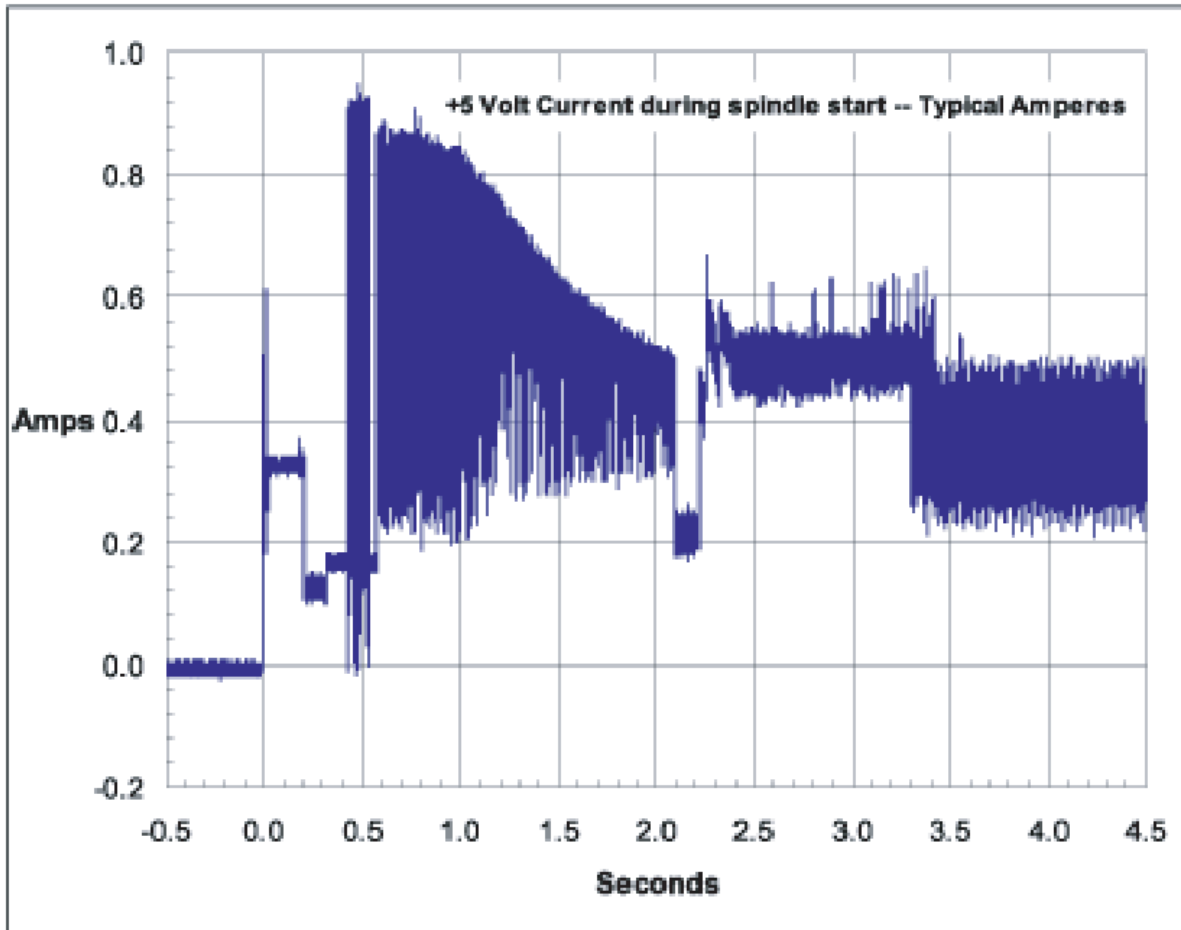


Figure 1. Typical 5V startup and operation current profile

### 2.9.2 Conducted noise

Input noise ripple is measured at the host system power supply across an equivalent 15-ohm resistive load on the +5 volt line.

Using 5-volt power, the drive is expected to operate with a maximum of 100 mV peak-to-peak square-wave injected noise at up to 10 MHz.

**Note.** Equivalent resistance is calculated by dividing the nominal voltage by the typical RMS read/write current.

### 2.9.3 Voltage tolerance

Voltage tolerance (including noise):

5V  $\pm$  5%

## 2.9.4 Power-management modes

The drive provides programmable power management to provide greater energy efficiency. In most systems, you can control power management through the system setup program. The drive features the following power-management modes:

**Table 3: Power management modes**

Power modes	Heads	Spindle	Buffer
Active (operating)	Tracking	Rotating	Enabled
Idle	Tracking	Rotating	Enabled
Idle, active	Floating	Rotating	Disabled
Idle, low power	Parked	Rotating	Disabled
Standby	Parked	Stopped	Enabled
Sleep	Parked	Stopped	Disabled

- **Active mode**

The drive is in Active mode during the read/write and seek operations.

- **Idle mode**

The buffer remains enabled in performance mode, and the drive accepts all commands and returns to Active mode any time disc access is necessary.

- **Standby mode**

The drive enters Standby mode when the host sends a Standby Immediate command. If the host has set the standby timer, the drive can also enter Standby mode automatically after the drive has been inactive for a specifiable length of time. The standby timer delay is established using a Standby or Idle command. In Standby mode, the drive buffer is enabled, the heads are parked and the spindle is at rest. The drive accepts all commands and returns to Active mode any time disc access is necessary.

- **Sleep mode**

The drive enters Sleep mode after receiving a Sleep command from the host. In Sleep mode, the drive buffer is disabled, the heads are parked and the spindle is at rest. The drive leaves Sleep mode after it receives a Hard Reset or Soft Reset from the host. After receiving a reset, the drive exits Sleep mode and enters Standby mode with all current translation parameters intact.

- **Idle and Standby timers**

Each time the drive performs an Active function (read, write or seek), the standby timer is reinitialized and begins counting down from its specified delay times to zero. If the standby timer reaches zero before any drive activity is required, the drive makes a transition to Standby mode. In both Idle and Standby mode, the drive accepts all commands and returns to Active mode when disc access is necessary.

## 2.10 Environmental specifications

### 2.10.1 Ambient temperature

Ambient temperature is defined as the temperature of the environment immediately surrounding the drive. Actual drive case temperature should not exceed 65°C (149°F) within the operating ambient conditions.

Above 1,000 feet (305 meters), the maximum temperature is derated linearly by 1°C every 1000 feet.

Operating	5° to 55°C (41° to 131°F)
Nonoperating	–40° to 70°C (–40° to 158°F)

### 2.10.2 Temperature gradient

Operating	20°C per hour (68°F per hour max), without condensation
Nonoperating	30°C per hour (86°F per hour max)

### 2.10.3 Humidity

#### 2.10.3.1 Relative humidity

Operating	8% to 90% noncondensing (30% per hour max)
Nonoperating	5% to 95% noncondensing (30% per hour max)

#### 2.10.3.2 Wet bulb temperature

Operating	30°C (86°F max)
Nonoperating	40°C (104°F max)

### 2.10.4 Altitude

Operating	–304.8 m to 3,048 m (–1,000 ft to 10,000 ft)
Nonoperating	–304.8 m to 12,192 m (–1,000 ft to 40,000 ft)



## 2.10.5 Shock

All shock specifications assume that the drive is mounted securely with the input shock applied at the drive mounting screws. Shock may be applied in the X, Y or Z axis.

### 2.10.5.1 Operating shock

These drives comply with the performance levels specified in this document when subjected to a maximum operating shock of 100 Gs based on half-sine shock pulses of 2 msec. Shocks should not be repeated more than two times per second.

### 2.10.5.2 Nonoperating shock

The nonoperating shock level that the drive can experience without incurring physical damage or degradation in performance when subsequently put into operation is 500 Gs based on a nonrepetitive half-sine shock pulse of 2 msec duration.

The nonoperating shock level that the drive can experience without incurring physical damage or degradation in performance when subsequently put into operation is 350 Gs based on a nonrepetitive half-sine shock pulse of 1 msec duration.

The nonoperating shock level that the drive can experience without incurring physical damage or degradation in performance when subsequently put into operation is 200 Gs based on a nonrepetitive half-sine shock pulse of 0.5 msec duration.

## 2.10.6 Vibration

All vibration specifications assume that the drive is mounted securely with the input vibration applied at the drive mounting screws. Vibration may be applied in the X, Y or Z axis.

### 2.10.6.1 Operating vibration

The following table lists the maximum vibration levels that the drive may experience while meeting the performance standards specified in this document.

22–350 Hz	0.5 Gs (0 to peak).
351-500 Hz	0.25 Gs

### 2.10.6.2 Nonoperating vibration

The following table lists the maximum nonoperating vibration that the drive may experience without incurring physical damage or degradation in performance when subsequently put into operation.

22–350 Hz	5.0 Gs (0 to peak)
351-500 Hz	1.0 G

## 2.11 Acoustics

Drive acoustics are measured as overall A-weighted acoustic sound power levels. All measurements are consistent with ISO document 7779. Sound power measurements are taken under essentially free-field conditions over a reflecting plane. For all tests, the drive is oriented with the cover facing upward.

**Note.** For seek mode tests, the drive is placed in seek mode only. The number of seeks per second is defined by the following equation:

$$(\text{Number of seeks per second} = 0.4 / (\text{average latency} + \text{average access time}))$$

**Table 4: Drive level acoustics**

Idle*	Seek
2.4 bels (typ)	2.7 bels (typ)

\*During periods of drive idle, some offline activity may occur according to the S.M.A.R.T. specification, which may increase acoustic and power to operational levels.

## 2.12 Electromagnetic immunity

When properly installed in a representative host system, the drive operates without errors or degradation in performance when subjected to the radio frequency (RF) environments defined in the following table:

**Table 5: Electromagnetic immunity**

Test	Description	Performance level	Reference standard
Electrostatic discharge	Contact, HCP, VCP: $\pm 4$ kV; Air: $\pm 8$ kV	B	EN 61000-4-2: 95
Radiated RF immunity	80 to 2,000 MHz, 10 V/m, 80% AM with 1 kHz sine 900 MHz, 3 V/m, 50% pulse modulation @ 200 Hz	A	EN 61000-4-3: 96 ENV 50204: 95
Electrical fast transient	$\pm 1$ kV on AC mains, $\pm 0.5$ kV on external I/O	B	EN 61000-4-4: 95
Surge immunity	$\pm 1$ kV differential, $\pm 2$ kV common, AC mains	B	EN 61000-4-5: 95
Conducted RF immunity	150 kHz to 80 MHz, 3 Vrms, 80% AM with 1 kHz sine	A	EN 61000-4-6: 97
Power Frequency H-field immunity	1 A/m, 50Hz/60Hz, 3 axes	A	EN 61000-4-8: 97
Voltage dips, interrupts	30% Reduction for 25 cycles >95% Reduction for 250 cycles >95%, 0.5 cycles	C C B	EN 61000-4-11: 94

A - 1) No upset or degradation in performance beyond manufacturer's specified limits.

2) No data loss.

B - 1) Unit self recovers without user intervention.

2) No data loss.

C - 1) Upset OK provided that unit will function after user intervention.

## 2.13 Reliability

Measurement type	Specification
Nonrecoverable read errors	1 per 10 <sup>14</sup> bits read, max.
Annualized Failure Rate (AFR)	<1.0% Desktop and Gaming use
Load/Unload (L/UL) Controlled L/UL cycles (40°C, 50% Relative Humidity)	50,000
Emergency L/UL cycles (40°C, 50% Relative Humidity)	20,000
Service Life	5 Years
Warranty	To determine the warranty for a specific drive, use a web browser to access the following web page: <a href="http://www.seagate.com/support/service/">www.seagate.com/support/service/</a> From this page, click on the “Verify Your Warranty” link. You will be asked to provide the drive serial number, model number (or part number) and country of purchase. The system will display the warranty information for your drive.

## 2.14 Agency certification

### 2.14.1 Safety certification

The drives are recognized in accordance with UL 1950 and CSA C22.2 (950) and meet all applicable sections of IEC950 and EN 60950 as tested by TUV North America.

### 2.14.2 Electromagnetic compatibility

Hard drives that display the CE mark comply with the European Union (EU) requirements specified in the Electromagnetic Compatibility Directive (89/336/EEC). Testing is performed to the levels specified by the product standards for Information Technology Equipment (ITE). Emission levels are defined by EN 55022, Class B and the immunity levels are defined by EN 55024.

Seagate uses an independent laboratory to confirm compliance with the EC directives specified in the previous paragraph. Drives are tested in representative end-user systems. Although CE-marked Seagate drives comply with the directives when used in the test systems, we cannot guarantee that all systems will comply with the directives. The drive is designed for operation inside a properly designed enclosure, with properly shielded I/O cable (if necessary) and terminators on all unused I/O ports. Computer manufacturers and system integrators should confirm EMC compliance and provide CE marking for their products.

## Korean RRL

If these drives have the Korea Ministry of Information and Communication (MIC) logo, they comply with paragraph 1 of Article 11 of the Electromagnetic Compatibility control Regulation and meet the Electromagnetic Compatibility (EMC) Framework requirements of the Radio Research Laboratory (RRL) Ministry of Information and Communication Republic of Korea.

These drives have been tested and comply with the Electromagnetic Interference/Electromagnetic Susceptibility (EMI/EMS) for Class B products. Drives are tested in a representative, end-user system by a Korean-recognized lab.

- EUT name (model numbers): ST9402115A and ST920217A.
- Certificate numbers:

ST9402115A	E-D011-05-2395(B)
ST920217A	E-D011-05-2395(B)
- Trade name or applicant: Seagate Technology International
- Manufacturing date: June 2005
- Manufacturer/nationality: Seagate Technology International

## Australian C-Tick (N176)

If these models have the C-Tick marking, they comply with the Australia/New Zealand Standard AS/NZS3548 1995 and meet the Electromagnetic Compatibility (EMC) Framework requirements of the Australian Communication Authority (ACA).

### 2.14.3 FCC verification

These drives are intended to be contained solely within a personal computer or similar enclosure (not attached as an external device). As such, each drive is considered to be a subassembly even when it is individually marketed to the customer. As a subassembly, no Federal Communications Commission verification or certification of the device is required.

Seagate Technology LLC has tested this device in enclosures as described above to ensure that the total assembly (enclosure, disc drive, motherboard, power supply, etc.) does comply with the limits for a Class B computing device, pursuant to Subpart J, Part 15 of the FCC rules. Operation with noncertified assemblies is likely to result in interference to radio and television reception.

**Radio and television interference.** This equipment generates and uses radio frequency energy and if not installed and used in strict accordance with the manufacturer's instructions, may cause interference to radio and television reception.

This equipment is designed to provide reasonable protection against such interference in a residential installation. However, there is no guarantee that interference will not occur in a particular installation. If this equipment does cause interference to radio or television, which can be determined by turning the equipment on and off, you are encouraged to try one or more of the following corrective measures:

- Reorient the receiving antenna.
- Move the device to one side or the other of the radio or TV.
- Move the device farther away from the radio or TV.
- Plug the computer into a different outlet so that the receiver and computer are on different branch outlets.

If necessary, you should consult your dealer or an experienced radio/television technician for additional suggestions. You may find helpful the following booklet prepared by the Federal Communications Commission: *How to Identify and Resolve Radio-Television Interference Problems*. This booklet is available from the Superintendent of Documents, U.S. Government Printing Office, Washington, DC 20402. Refer to publication number 004-000-00345-4.

## **2.15 Environmental protection**

Seagate designs its products to meet environmental protection requirements worldwide, including regulations restricting certain chemical substances.

### **2.15.1 European Union Restriction of Hazardous Substances (RoHS)**

A new law, the European Union Restriction of Hazardous Substances (RoHS) directive, will restrict the presence of chemical substances, including Lead (Pb), in electronic products effective July 2006.

A number of parts and materials in Seagate products are procured from external suppliers. We rely on the representations of our suppliers regarding the presence of RoHS substances in these parts and materials. Our supplier contracts require compliance with our chemical substance restrictions, and our suppliers document their compliance with our requirements by providing material content declarations for all parts and materials for the disc drives documented in this publication. Current supplier declarations include disclosure of the inclusion of any RoHS-regulated substance in such parts or materials.

Seagate also has internal systems in place to ensure ongoing compliance with the RoHS Directive and all laws and regulations which restrict chemical content in electronic products. These systems include standard operating procedures that ensure that restricted substances are not utilized in our manufacturing operations, laboratory analytical validation testing, and an internal auditing process to ensure that all standard operating procedures are complied with.

## **2.16 Corrosive environment**

Seagate electronic drive components pass accelerated corrosion testing equivalent to 10 years exposure to light industrial environments containing sulfurous gases, chlorine and nitric oxide, classes G and H per ASTM B845. However, this accelerated testing cannot duplicate every potential application environment.

Users should use caution exposing any electronic components to uncontrolled chemical pollutants and corrosive chemicals as electronic drive component reliability can be affected by the installation environment. The silver, copper, nickel and gold films used in Seagate products are especially sensitive to the presence of sulfide, chloride, and nitrate contaminants. Sulfur is found to be the most damaging. In addition, electronic components should never be exposed to condensing water on the surface of the printed circuit board assembly (PCBA) or exposed to an ambient relative humidity greater than 95%. Materials used in cabinet fabrication, such as vulcanized rubber, that can outgas corrosive compounds should be minimized or eliminated. The useful life of any electronic equipment may be extended by replacing materials near circuitry with sulfide-free alternatives.



## 3.0 Configuring and mounting the drive

---

This section contains the specifications and instructions for configuring and mounting the drive.

### 3.1 Handling and static discharge precautions

After unpacking, and before installation, the drive may be exposed to potential handling and electrostatic discharge (ESD) hazards. Observe the following standard handling and static-discharge precautions:

**Caution:**

- Keep the drive in the electrostatic discharge (ESD) bag until you are ready for installation to limit the drive's exposure to ESD.
- Before handling the drive, put on a grounded wrist strap, or ground yourself frequently by touching the metal chassis of a computer that is plugged into a grounded outlet. Wear a grounded wrist strap throughout the entire installation procedure.
- Handle the drive only by its edges or frame.
- The drive is fragile—handle it with care. Do not press down on the drive top cover.
- Always rest the drive on a padded, antistatic surface until you mount it in the computer.
- Do not touch the connector pins or the printed circuit board.
- Do not remove the factory-installed labels from the drive or cover them with additional labels. Removal voids the warranty. Some factory-installed labels contain information needed to service the drive. Other labels are used to seal out dirt and contamination.

### 3.2 Jumper settings

#### 3.2.1 Master/slave configuration

Use the options jumper block shown in Figure 2 to configure the drive for operation. This jumper block is the 4-pin header adjacent to pins 1 and 2 of the I/O signal pins. For additional information about using the Cable select option, see Section 3.2.2.

The “Master or single drive” option is the factory default setting.

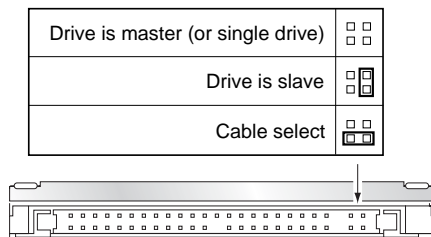


Figure 2. Jumper settings

### **3.2.2 Cable-select option**

Computers that use cable select determine the master and slave drives by selecting or deselecting pin 28, CSEL, on the interface bus. Master and slave drives are determined by their physical position on the cable. To enable cable select, set a jumper as shown in Figure 2. Refer to your computer manual to determine whether your computer supports this option.



### 3.3 Drive mounting

You can mount the drive using four screws in the side-mounting holes or four screws in the bottom-mounting holes. See Figure 3 for drive mounting dimensions (dimensions in inches with mm in parentheses). Follow these important mounting precautions when mounting the drive:

- Allow a minimum clearance of 0.030 inches (0.76 mm) around the entire perimeter of the drive for cooling.
- Use only M3 x 0.5 mounting screws.
- Do not overtighten the mounting screws (maximum torque: 4.0 inch-lb).
- Four (4) threads (0.080 inches) minimum screw engagement recommended.

Dimensions shown below are in inches.

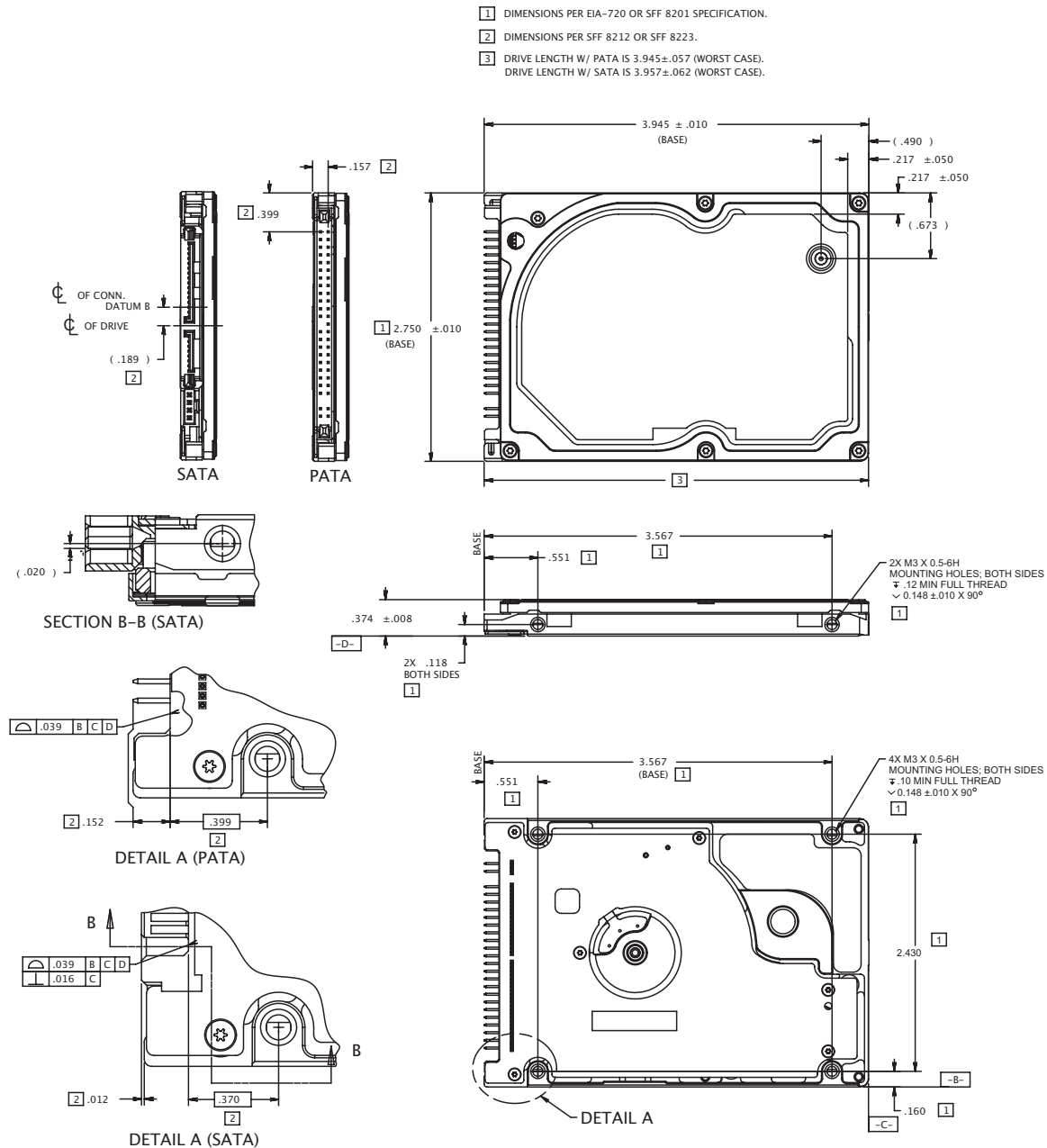


Figure 3. Mounting dimensions—top, side and end view



## 4.0 ATA interface

These drives use the industry-standard ATA task file interface that supports 16-bit data transfers. It supports ATA programmed input/output (PIO) modes 0–4; multiword DMA modes 0–2, and Ultra DMA modes 0–5. The drive also supports the use of the IORDY signal to provide reliable high-speed data transfers.

For detailed information about the ATA interface, refer to the draft of *AT Attachment with Packet Interface Extension (ATA/ATAPI-6)*, *NCITS T13 1410D*, subsequently referred to as the *Draft ATA-6 Standard*.

### 4.1 ATA interface signals and connector pins

The following table summarizes the signals on the 44-pin ATA interface connector. For a detailed description of these signals, refer to the *Draft ATA-6 Standard*.

**Table 6: Connector signals**

Signal Name	Connector Contact	Cable Conductor
RESET-	1	1
DD7	3	3
DD6	5	5
DD5	7	7
DD4	9	9
DD3	11	11
DD2	13	13
DD1	15	15
DD0	17	17
Ground	19	19
DMARQ	21	21
DIOW-	23	23
DIOR-	25	25
IORDY	27	27
DMACK-	29	29
INTRQ	31	31
DA1	33	33
DA0	35	35
CS1FX-	37	37
DASP-	39	39
+5 V (Logic)	41	41
Ground (Return)	43	43

Cable Conductor	Connector Contact	Signal Name
2	2	Ground
4	4	DD8
6	6	DD9
8	8	DD10
10	10	DD11
12	12	DD12
14	14	DD13
16	16	DD14
18	18	DD15
20	20	(keypin)
22	22	Ground
24	24	Ground
26	26	Ground
28	28	PSYNC:CSEL
30	30	Ground
32	32	IOCS16-
34	34	PDIAG-
36	36	DA2
38	38	CS3FX-
40	40	Ground
42	42	+5V (Motor)
44	44	No connection

#### 4.1.1 Supported ATA commands

The following table lists ATA-standard commands that the drive supports. For a detailed description of the ATA commands, refer to the *Draft ATA-6 Standard*...

**Table 7: Supported commands**

Command name	Command code (in hex)
<b>ATA-standard commands</b>	
ATA Device Configuration Overlay	B1 <sub>H</sub>
ATA Service	A2 <sub>H</sub>
Check Power Mode	98 <sub>H</sub> , E5 <sub>H</sub>
Download Microcode	92 <sub>H</sub>
Execute Device Diagnostics	90 <sub>H</sub>
Flush Cache	E7 <sub>H</sub>
Flush Cache Extended	EA <sub>H</sub>
Format Track (Legacy)	50 <sub>H</sub>
Identify Device	EC <sub>H</sub>
Idle	97 <sub>H</sub> , E3 <sub>H</sub>
Idle Immediate	95 <sub>H</sub> , E1 <sub>H</sub>
Initialize Device Parameters	91 <sub>H</sub>
Read Buffer	E4 <sub>H</sub>
Read DMA	C8 <sub>H</sub> , C9 <sub>H</sub>
Read DMA Extended	25 <sub>H</sub>
Read Log Extended	22 <sub>H</sub>
Read Multiple	C4 <sub>H</sub>
Read Multiple Extended	29 <sub>H</sub>
Read Native Max Address	F8 <sub>H</sub>
Read Native Max Address Extended	27 <sub>H</sub>
Read Sectors	20 <sub>H</sub> , 21 <sub>H</sub>
Read Sectors Extended	24 <sub>H</sub>
Read Verify Sectors	40 <sub>H</sub> , 41 <sub>H</sub>
Read Verify Sectors Extended	42 <sub>H</sub>
Recalibrate	10 <sub>H</sub>
Security Disable Password	F6 <sub>H</sub>
Security Erase Prepare	F3 <sub>H</sub>
Security Erase Unit	F4 <sub>H</sub>
Security Freeze Lock	F5 <sub>H</sub>
Security Set Password	F1 <sub>H</sub>

**Table 7: Supported commands**

Command name	Command code (in hex)
Security Unlock	F2 <sub>H</sub>
Seek	70 <sub>H</sub>
Set Drive Parameters	91 <sub>H</sub>
Set Features	EF <sub>H</sub>
Set Max Address	F9 <sub>H</sub>
Note: Individual Set Max commands are identified by the value placed in the Set Max Features register as defined to the right.	Address 00 <sub>H</sub> Password 01 <sub>H</sub> Lock 02 <sub>H</sub> Unlock 03 <sub>H</sub> Freeze Lock 04 <sub>H</sub>
Set Multiple Mode	C6 <sub>H</sub>
Sleep	99 <sub>H</sub> , E6 <sub>H</sub>
S.M.A.R.T.	B0 <sub>H</sub>
Standby	96 <sub>H</sub> , E2 <sub>H</sub>
Standby Immediate	94 <sub>H</sub> , E0 <sub>H</sub>
Vendor Unique	9A <sub>H</sub> , FA <sub>H</sub> , FB <sub>H</sub>
Write Buffer	E8 <sub>H</sub>
Write DMA	CA <sub>H</sub> , CB <sub>H</sub>
Write DMA Extended	35 <sub>H</sub>
Write Log Extended	32 <sub>H</sub>
Write Multiple	C5 <sub>H</sub>
Write Multiple Extended	39 <sub>H</sub>
Write Sectors	30 <sub>H</sub> , 31 <sub>H</sub>
Write Sectors Extended	34 <sub>H</sub>
<b>ATA-standard power-management commands</b>	
Check Power Mode	98 <sub>H</sub> or E5 <sub>H</sub>
Idle	97 <sub>H</sub> or E3 <sub>H</sub>
Idle Immediate	95 <sub>H</sub> or E1 <sub>H</sub>
Sleep	99 <sub>H</sub> or E6 <sub>H</sub>
Standby	96 <sub>H</sub> or E2 <sub>H</sub>
Standby Immediate	94 <sub>H</sub> or E0 <sub>H</sub>
<b>ATA-standard security commands</b>	
Security Set Password	F1 <sub>H</sub>
Security Unlock	F2 <sub>H</sub>
Security Erase Prepare	F3 <sub>H</sub>
Security Erase Unit	F4 <sub>H</sub>

**Table 7: Supported commands**

<b>Command name</b>	<b>Command code (in hex)</b>
Security Freeze Lock	F5 <sub>H</sub>
Security Disable Password	F6 <sub>H</sub>

#### 4.1.2 Identify Device command

The Identify Device command (command code EC<sub>H</sub>) transfers information about the drive to the host following power up. The data is organized as a single 512-byte block of data, whose contents are shown in Table 7 on page 22. All reserved bits or words should be set to zero. Parameters listed with an “x” are drive-specific or vary with the state of the drive. See Section 2.0 on page 3 for default parameter settings.

The following commands contain drive-specific features that may not be included in the *Draft ATA-6 Standard*.

Word	Description	Value
0	Configuration information: <ul style="list-style-type: none"> <li>• Bit 15: 0 = ATA; 1 = ATAPI</li> <li>• Bit 7: removable media</li> <li>• Bit 6: removable controller</li> <li>• Bit 0: reserved</li> </ul>	0C5A <sub>H</sub>
1	Number of logical cylinders	16,383
2	ATA-reserved	0000 <sub>H</sub>
3	Number of logical heads	16
4	Retired	0000 <sub>H</sub>
5	Retired	0000 <sub>H</sub>
6	Number of logical sectors per logical track: 63	003F <sub>H</sub>
7–9	Retired	0000 <sub>H</sub>
10–19	Serial number: (20 ASCII characters, 0000 <sub>H</sub> = none)	ASCII
20	Retired	0000 <sub>H</sub>
21	Retired	0400 <sub>H</sub>
22	Obsolete	0000 <sub>H</sub>
23–26	Firmware revision (8 ASCII character string, padded with blanks to end of string)	x.xx
27–46	Drive model number (40 ASCII characters, padded with blanks to end of string)	ST9402115A ST920217A
47	(Bits 7–0) Maximum sectors per interrupt on Read multiple and Write multiple (16)	8010 <sub>H</sub>
48	Reserved	0000 <sub>H</sub>
49	Standard Standby timer, IORDY supported and may be disabled	2F00 <sub>H</sub>
50	ATA-reserved	0000 <sub>H</sub>
51	PIO data-transfer cycle timing mode	0200 <sub>H</sub>
52	Retired	0200 <sub>H</sub>
53	Words 54–58, 64–70 and 88 are valid	0007 <sub>H</sub>
54	Number of current logical cylinders	xxxx <sub>H</sub>
55	Number of current logical heads	xxxx <sub>H</sub>
56	Number of current logical sectors per logical track	xxxx <sub>H</sub>
57–58	Current capacity in sectors	xxxx <sub>H</sub>
59	Number of sectors transferred during a Read Multiple or Write Multiple command	xxxx <sub>H</sub>

Word	Description	Value
60–61	Total number of user-addressable LBA sectors available (see Section 2.2 for related information)	ST9402115A = 82,443,600 ST920217A = 41,021,800
62	Retired	0000 <sub>H</sub>
63	Multiword DMA active and modes supported (see note following this table)	xx07 <sub>H</sub>
64	Advanced PIO modes supported (modes 3 and 4 supported)	0003 <sub>H</sub>
65	Minimum multiword DMA transfer cycle time per word (120 nsec)	0078 <sub>H</sub>
66	Recommended multiword DMA transfer cycle time per word (120 nsec)	0078 <sub>H</sub>
67	Minimum PIO cycle time without IORDY flow control (240 nsec)	00F0 <sub>H</sub>
68	Minimum PIO cycle time with IORDY flow control (120 nsec)	0078 <sub>H</sub>
69–74	ATA-reserved	0000 <sub>H</sub>
75	Queue depth	0000 <sub>H</sub>
76–79	ATA-reserved	0000 <sub>H</sub>
80	Major version number	007E <sub>H</sub>
81	Minor version number	0000 <sub>H</sub>
82	Command sets supported	346B <sub>H</sub>
83	Command sets supported	7D01 <sub>H</sub>
84	Command sets support extension	4003 <sub>H</sub>
85	Command sets enabled	34xx <sub>H</sub>
86	Command sets enabled	3xxx <sub>H</sub>
87	Command sets enable extension	4003 <sub>H</sub>
88	Ultra DMA support and current mode (see note following this table)	xx3F <sub>H</sub>
89	Security erase time	0000 <sub>H</sub>
90	Enhanced security erase time	0000 <sub>H</sub>
91	Advanced power management value	0040 <sub>H</sub>
92	Master password revision code	FFFE <sub>H</sub>
93	Hardware reset value (see description following this table)	xxxx <sub>H</sub>
94	Auto acoustic management setting	xxxx <sub>H</sub>
95–127	ATA-reserved	0000 <sub>H</sub>
128	Security status	0001 <sub>H</sub>
129–159	Seagate-reserved	xxxx <sub>H</sub>
160–254	ATA-reserved	0000 <sub>H</sub>
255	Integrity word	xxA5 <sub>H</sub>

**Note.** See the bit descriptions below for words 63, 88, 93 and 94 of the Identify Drive data.



<b>Description (if bit is set to 1)</b>		
	<b>Bit</b>	<b>Word 63</b>
	0	Multiword DMA mode 0 is supported.
	1	Multiword DMA mode 1 is supported.
	2	Multiword DMA mode 2 is supported.
	8	Multiword DMA mode 0 is currently active.
	9	Multiword DMA mode 1 is currently active.
	10	Multiword DMA mode 2 is currently active.
	<b>Bit</b>	<b>Word 88</b>
	0	Ultra DMA mode 0 is supported.
	1	Ultra DMA mode 1 is supported.
	2	Ultra DMA mode 2 is supported.
	3	Ultra DMA mode 3 is supported.
	4	Ultra DMA mode 4 is supported.
	8	Ultra DMA mode 0 is currently active.
	9	Ultra DMA mode 1 is currently active.
	10	Ultra DMA mode 2 is currently active.
	11	Ultra DMA mode 3 is currently active.
	12	Ultra DMA mode 4 is currently active.
	13	Ultra DMA mode 5 is currently active.
	<b>Bit</b>	<b>Word 93</b>
	13	1 = 80-conductor cable detected, CBLID above $V_{IH}$ 0 = 40-conductor cable detected, CBLID below $V_{IL}$

### 4.1.3 Set Features command

This command controls the implementation of various features that the drive supports. When the drive receives this command, it sets BSY, checks the contents of the Features register, clears BSY and generates an interrupt. If the value in the register does not represent a feature that the drive supports, the command is aborted. Power-on default has the read look-ahead and write caching features enabled. The acceptable values for the Features register are defined as follows:

**Table 8: Features register values**

02 <sub>H</sub>	Enable write cache ( <i>default</i> ).	
03 <sub>H</sub>	Set transfer mode (based on value in Sector Count register).	
	Sector Count register values:	
	00 <sub>H</sub>	Set PIO mode to default (PIO mode 2).
	01 <sub>H</sub>	Set PIO mode to default and disable IORDY (PIO mode 2).
	08 <sub>H</sub>	PIO mode 0
	09 <sub>H</sub>	PIO mode 1
	0A <sub>H</sub>	PIO mode 2
	0B <sub>H</sub>	PIO mode 3
	0C <sub>H</sub>	PIO mode 4 ( <i>default</i> )
	20 <sub>H</sub>	Multiword DMA mode 0
	21 <sub>H</sub>	Multiword DMA mode 1
	22 <sub>H</sub>	Multiword DMA mode 2
	40 <sub>H</sub>	Ultra DMA mode 0
	41 <sub>H</sub>	Ultra DMA mode 1
	42 <sub>H</sub>	Ultra DMA mode 2
	43 <sub>H</sub>	Ultra DMA mode 3
	44 <sub>H</sub>	Ultra DMA mode 4
	45 <sub>H</sub>	Ultra DMA mode 5
05 <sub>H</sub>	Enable advanced power management	
55 <sub>H</sub>	Disable read look-ahead (read cache) feature.	
82 <sub>H</sub>	Disable write cache.	
AA <sub>H</sub>	Enable read look-ahead (read cache) feature ( <i>default</i> ).	
F1 <sub>H</sub>	Report full capacity available	

**Note.** At power-on or after a hardware or software reset the default values of the features are as indicated above.

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# Index

## Numerics

3D Defense System 1

## A

acoustics 12  
Active mode 9  
AFR 13  
agency certification (regulatory) 13  
altitude 10  
ambient conditions 3  
ambient temperature 6, 10  
Annualized Failure Rate 13  
areal density 5  
ATA interface 21  
ATA-standard commands 22  
Australian C-Tick 14  
average seek time 6

## B

BPI 5  
buffer 1, 5  
burst 1

## C

cable-select option 18  
cache 1, 5  
case temperature 10  
CE mark 13  
certification 13  
Check Power Mode 23  
commands 22  
compliance 13  
conducted noise 8  
conducted RF immunity 12  
configuring the drive 17  
connector pins 21  
CSA C22.2 (950) 13  
CSEL 18  
C-Tick 14  
current profile 8

## D

Data Defense 1  
data-transfer rates 1  
DC power 7  
density 5  
Diagnostic Defense 1  
diagnostic software 1  
discs 5  
dissipation 7

Download Microcode 22  
Drive Defense 1  
drive diagnostics 6  
drive monitoring 1  
drive self-test 1

## E

electrical fast transient 12  
electromagnetic compatibility 13  
Electromagnetic Compatibility Directive 13  
electromagnetic immunity 12  
electrostatic discharge 12  
EMC compliance 13  
EN 60950 13  
enclosures 14  
environmental specifications 10  
error-correction algorithms 1  
errors 13  
European Union 13  
European Union Restriction of Hazardous Substances 15  
Execute Device Diagnostics 22

## F

FCC verification 14  
Features register 28  
Flush Cache 22  
Flush Cache Extended 22  
formatted capacity 5  
frequency 12

## G

guaranteed sectors 5

## H

handling 17  
Hazardous Substances 15  
heads 1, 5  
height 6  
humidity 10

## I

I/O data-transfer rate 5  
Identify Device 22  
Identify Device command 25  
Idle 7, 23  
Idle and Standby timers 9  
Idle Immediate 23  
Idle mode 9  
Idle mode power 7  
IEC950 13  
Information Technology Equipment 13  
Initialize Device Parameters 22

- interface 5, 21
- interface signals 21
- interference 14
- interleave 5
- internal data-transfer rate OD 5
- ISO document 7779 12

## J

- jumper settings 17

## K

- Korean RRL 14

## L

- LBA mode 5
- length 6
- Load/Unload 13
- logical geometry 5

## M

- Master/slave configuration 17
- maximum temperature 10
- modes 21
- monitoring 1
- mounting the drive 17, 19

## N

- noise 8
- nominal power 3
- nonoperating shock 11
- nonoperating vibration 11
- nonrecoverable read errors 13

## O

- operating shock 11
- operating vibration 11

## P

- physical characteristics 6
- physical organization 5
- pins 21
- PIO 21
- power consumption 7
- power dissipation 7
- power frequency h-field immunity 12
- power management 9
- power specifications 7
- power-management commands 23
- power-management modes 9
- Power-on to Ready 6
- precautions 19
- programmable power management 9

## R

- radiated RF immunity 12
- radio and television interference 14
- radio frequency (RF) 12
- random track location 7
- Read Buffer 22
- Read DMA 22
- Read DMA Extended 22
- read errors 13
- Read Multiple 1, 22
- Read Multiple Extended 22
- Read Native Max Address 22
- Read Native Max Address Extended 22
- Read Sectors 22
- Read Sectors Extended 22
- Read Verify Sectors 22
- Read Verify Sectors Extended 22
- read/write heads 5
- read/write power and current 7
- recording and interface technology 5
- recording density 5
- recording heads 1
- register 28
- relative humidity 10
- reliability 13
- resistance 8
- RF 12
- RoHS 15

## S

- S.M.A.R.T. 23
- S.M.A.R.T. drive monitoring 1
- safety certification 13
- screws 19
- SeaTools 1
- sectors 5
- security commands 23
- Security Disable Password 24
- Security Erase Prepare 23
- Security Erase Unit 23
- Security Freeze Lock 24
- Security Set Password 23
- Security Unlock 23
- Seek 23
- seek mode 7
- seek time 6
- Seeking 7
- Service Life 13
- servo electronics 7
- Set Features 23
- Set Features command 28
- Set Max 23
- Set Multiple Mode 23
- shock 11

- signals 21
- single-track seeks 6
- Sleep 23
- Sleep mode 9
- sound 12
- specifications 3
- spindle speed 5
- Spinup 7
- spinup power 7
- Standby 7, 23
- Standby Immediate 23
- Standby mode 7, 9
- Standby to Ready 6
- static-discharge precautions 17
- subassembly 14
- support services 29
- surge immunity 12

## **T**

- technical support services 29
- temperature 10
- temperature gradient 10
- time to ready 6
- timers 9
- TMR 1
- track density 5
- track-to-track seek time 6
- TUV North America 13

## **U**

- UL 1950 13

## **V**

- vibration 11
- voltage 8
- voltage dips, interrupts 12
- voltage tolerance 8

## **W**

- Warranty 13
- weight 6
- wet bulb temperature 10
- width 6
- Write Buffer 23
- Write DMA 23
- Write DMA Extended 23
- Write Multiple 1, 23
- Write Multiple Extended 23
- Write Sectors 23
- Write Sectors Extended 23









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