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Product Manual

Barracuda XT Series SATA

ST32000641AS

100586689
Rev. A
September 2009

Revision history

Revision	Date	Sheets affected or comments
Rev. A	09/15/2009	Initial release.

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When referring to hard drive capacity, one gigabyte, or GB, equals one billion bytes and one terabyte, or TB, equals one trillion bytes. Your computer's operating system may use a different standard of measurement and report a lower capacity. In addition, some of the listed capacity is used for formatting and other functions, and thus will not be available for data storage. Seagate reserves the right to change, without notice, product offerings or specifications.

Contents

1.0	Introduction	1
1.1	About the Serial ATA interface	2
2.0	Drive specifications	3
2.1	Formatted capacity	5
2.1.1	LBA mode	5
2.2	Default logical geometry	5
2.3	Recording and interface technology	5
2.4	Physical characteristics	6
2.5	Start/stop times	6
2.6	Power specifications	7
2.6.1	Power consumption	7
2.6.2	Conducted noise	9
2.6.3	Voltage tolerance	9
2.6.4	Power management modes	9
2.7	Environmental specifications	10
2.7.1	Ambient temperature	10
2.7.2	Temperature gradient	10
2.7.3	Humidity	10
2.7.4	Altitude	10
2.7.5	Shock	11
2.7.6	Vibration	11
2.8	Acoustics	12
2.8.1	Test for Prominent Discrete Tones (PDTs)	12
2.9	Electromagnetic immunity	12
2.10	Reliability	13
2.10.1	Annualized Failure Rate (AFR) and Mean Time Between Failures (MTBF)	13
2.11	Agency certification	13
2.11.1	Safety certification	13
2.11.2	Electromagnetic Compatibility (EMC)	13
2.11.3	FCC verification	14
2.12	Environmental protection	15
2.12.1	European Union Restriction of Hazardous Substances (RoHS) Directive	15
2.12.2	China Restriction of Hazardous Substances (RoHS) Directive	15
2.13	Corrosive environment	15
3.0	Configuring and mounting the drive	16
3.1	Handling and static-discharge precautions	16
3.2	Configuring the drive	17
3.3	Serial ATA cables and connectors	17
3.4	Drive mounting	18
4.0	Serial ATA (SATA) interface	19
4.1	Hot-Plug compatibility	19
4.2	Serial ATA device plug connector pin definitions	20
4.3	Supported ATA commands	21
4.3.1	Identify Device command	23
4.3.2	Set Features command	27
4.3.3	S.M.A.R.T. commands	28
5.0	Seagate Technology support services	29

List of Figures

Figure 1.	Attaching SATA cabling	17
Figure 2.	Mounting dimensions (2000GB model).....	18

1.0 Introduction

This manual describes the functional, mechanical and interface specifications for the following Seagate Barracuda® XT Series model drives:

ST32000641AS

These drives provide the following key features:

- The SATA 6Gb/s interface enables the use of the industry's newest and fastest hard drive controllers while providing backward compatibility to legacy SATA 1.5Gb/s or 3Gb/s systems.
- 7,200 RPM spindle speed.
- High instantaneous (burst) data-transfer rates (up to 600 Mbytes per second).
- Perpendicular recording technology provides the drives with increased areal density.
- State-of-the-art cache and on-the-fly error-correction algorithms.
- Native Command Queueing with command ordering to increase performance in demanding applications.
- Full-track multiple-sector transfer capability without local processor intervention.
- Compliant with RoHS requirements in China and Europe.
- SeaTools diagnostic software performs a drive self-test that eliminates unnecessary drive returns.
- Support for S.M.A.R.T. drive monitoring and reporting.
- Supports latching SATA cables and connectors.
- Worldwide Name (WWN) capability uniquely identifies the drive.

1.1 About the Serial ATA interface

The Serial ATA interface provides several advantages over the traditional (parallel) ATA interface. The primary advantages include:

- Easy installation and configuration with true plug-and-play connectivity. It is not necessary to set any jumpers or other configuration options.
- Thinner and more flexible cabling for improved enclosure airflow and ease of installation.
- Scalability to higher performance levels.

In addition, Serial ATA makes the transition from parallel ATA easy by providing legacy software support. Serial ATA was designed to allow you to install a Serial ATA host adapter and Serial ATA disk drive in your current system and expect all of your existing applications to work as normal.

The Serial ATA interface connects each disk drive in a point-to-point configuration with the Serial ATA host adapter. There is no master/slave relationship with Serial ATA devices like there is with parallel ATA. If two drives are attached on one Serial ATA host adapter, the host operating system views the two devices as if they were both “masters” on two separate ports. This essentially means both drives behave as if they are Device 0 (master) devices.

Note. The host adapter may, optionally, emulate a master/slave environment to host software where two devices on separate Serial ATA ports are represented to host software as a Device 0 (master) and Device 1 (slave) accessed at the same set of host bus addresses. A host adapter that emulates a master/slave environment manages two sets of shadow registers. This is not a typical Serial ATA environment.

The Serial ATA host adapter and drive share the function of emulating parallel ATA device behavior to provide backward compatibility with existing host systems and software. The Command and Control Block registers, PIO and DMA data transfers, resets, and interrupts are all emulated.

The Serial ATA host adapter contains a set of registers that shadow the contents of the traditional device registers, referred to as the Shadow Register Block. All Serial ATA devices behave like Device 0 devices. For additional information about how Serial ATA emulates parallel ATA, refer to the “Serial ATA International Organization: Serial ATA Revision 2.6”. The specification can be downloaded from www.sata-io.org.

2.0 Drive specifications

Unless otherwise noted, all specifications are measured under ambient conditions, at 25°C, and nominal power. For convenience, the phrases *the drive* and *this drive* are used throughout this manual to indicate the following drive models:

ST32000641AS

The specification summaries listed in the following tables are for quick reference. For details on specification measurement or definition, see the appropriate section of this manual.

Table 1: Drive specifications summary for 2000 Gbyte models

Drive specification	ST32000641AS
Formatted capacity (512 bytes/sector)*	2000 Gbytes
Guaranteed sectors	3,907,029,168
Heads	8
Disks	4
Bytes per sector	512
Default sectors per track	63
Default read/write heads	16
Default cylinders	16,383
Recording density	1421 kbits/in
Track density	240 ktracks/in avg
Areal density	347 Gbits/in ² avg
Spindle speed	7,200 RPM
Internal data transfer rate	1300 Mbits/sec max
Sustained data transfer rate OD	138 Mbytes/sec max
I/O data-transfer rate	600 Mbytes/sec max
ATA data-transfer modes supported	PIO modes 0–4 Multiword DMA modes 0–2 Ultra DMA modes 0–6
Cache buffer	64 Mbytes
Height (max)	26.1 mm (1.028 inches)
Width (max)	101.85 mm (4.010 inches)
Length (max)	146.99 mm (5.787 inches)
Weight (typical)	700 grams (1.543 lb.)
Average latency	4.16 msec
Power-on to ready	15 sec typical
Standby to ready	15 sec typical
Startup current (typical) 12V (peak)	2.8 amps

Drive specification	ST32000641AS
Voltage tolerance (including noise)	5V +5% / -5% 12V +10% / -10%
Operating temperature (Drive Case temperature)	0° to 60°C
Nonoperating temperature (Ambient)	-40° to 70°C
Temperature gradient (max)	20°C per hour max (operating) 30°C per hour max (nonoperating)
Relative humidity	5% to 95% (operating) 5% to 95% (nonoperating)
Relative humidity gradient	30% per hour max
Wet bulb temperature (max)	37.7°C max (operating) 40.0°C max (nonoperating)
Altitude, operating	-60.96 m to 3,048 m (-200 ft. to 10,000+ ft.)
Altitude, nonoperating (below mean sea level, max)	-60.96 m to 12,192 m (-200 ft. to 40,000+ ft.)
Operational Shock	63 Gs at 2 msec max
Non-Operational Shock	300 Gs at 2 msec max
Vibration, operating	5-350 Hz: 0.50 Gs 350-500 Hz: 0.25 Gs
Vibration, nonoperating	5-350 Hz: 5.0 Gs 350-500 Hz: 2.0 Gs
Drive acoustics, sound power	
Idle**	2.7 bels (typical) 2.9 bels (max)
Performance	2.9 bels (typical) 3.3 bels (max)
Nonrecoverable read errors	1 per 10 ¹⁴ bits read
Annualized Failure Rate (AFR)	0.34%
Warranty	To determine the warranty for a specific drive, use a web browser to access the following web page: support.seagate.com/customer/warranty_validation.jsp From this page, click on the "Verify Your Warranty" link. You will be asked to provide the drive serial number, model number (or part number) and country of purchase. The system will display the warranty information for your drive.
Load-unload cycles	300,000 at 25°C, 50% rel. humidity
Supports Hotplug operation per the Serial ATA Revision 2.6 specification	Yes

*One Gbyte equals one billion bytes when referring to hard drive capacity. Accessible capacity may vary depending on operating environment and formatting.

**During periods of drive idle, some offline activity may occur according to the S.M.A.R.T. specification, which may increase acoustic and power to operational levels.

2.1 Formatted capacity

Model	Formatted capacity*	Guaranteed sectors	Bytes per sector
ST32000641AS	2000 Gbytes	3,907,029,168	512

*One Gbyte equals one billion bytes when referring to hard drive capacity. Accessible capacity may vary depending on operating environment and formatting.

2.1.1 LBA mode

When addressing these drives in LBA mode, all blocks (sectors) are consecutively numbered from 0 to $n-1$, where n is the number of guaranteed sectors as defined above.

See Section 4.3.1, "Identify Device command" (words 60-61 and 100-103) for additional information about 48-bit addressing support of drives with capacities over 137 Gbytes.

2.2 Default logical geometry

Cylinders	Read/write heads	Sectors per track
16,383	16	63

LBA mode

When addressing these drives in LBA mode, all blocks (sectors) are consecutively numbered from 0 to $n-1$, where n is the number of guaranteed sectors as defined above.

2.3 Recording and interface technology

Interface	Serial ATA (SATA)
Recording method	Perpendicular
Recording density (kbits/inch max)	1421 kbits/in
Track density (ktracks/inch avg)	240 ktracks/in avg
Areal density (Gbits/inch ² avg)	347 Gbits/in ² avg
Spindle speed (RPM)	7,200 +/- 0.2%
Internal data transfer rate (Mbits/sec max)	1300 Mbits/sec max
Sustained data transfer rate (Mbytes/sec max)	138 Mbytes/sec max
I/O data-transfer rate (Mbytes/sec max)	600 Mbytes/sec max

2.4 Physical characteristics

	ST32000641AS
Maximum height	26.1 mm (1.028 inches)
Maximum width	101.85 mm (4.010 inches)
Maximum length	146.99 mm (5.787 inches)
Typical weight	700 grams (1.543 lb.)
Cache buffer	64 Mbytes (64,768 kbytes)

2.5 Start/stop times

	2000GB model
Power-on to ready (sec)	15.0 (max)
Standby to ready (sec)	15.0 (max)
Ready to spindle stop (sec)	20.0 (max)

2.6 Power specifications

The drive receives DC power (+5V or +12V) through a native SATA power connector. See Figure 1 on page 17.

2.6.1 Power consumption

Power requirements for the drives are listed in the table on page 9. Typical power measurements are based on an average of drives tested, under nominal conditions, using 5.0V and 12.0V input voltage at 25°C ambient temperature.

- **Spinup power**

Spinup power is measured from the time of power-on to the time that the drive spindle reaches operating speed.

- **Seek mode**

During seek mode, the read/write actuator arm moves toward a specific position on the disk surface and does not execute a read or write operation. Servo electronics are active. Seek mode power represents the worst-case power consumption, using only random seeks with read or write latency time. This mode is not typical and is provided for worst-case information.

- **Read/write power and current**

Read/write power is measured with the heads on track, based on a 16-sector write followed by a 32-msec delay, then a 16-sector read followed by a 32-msec delay.

- **Operating power and current**

Operating power is measured using 40 percent random seeks, 40 percent read/write mode (1 write for each 10 reads) and 20 percent drive idle mode.

- **Idle mode power**

Idle mode power is measured with the drive up to speed, with servo electronics active and with the heads in a random track location.

- **Standby mode**

During standby mode, the drive accepts commands, but the drive is not spinning, and the servo and read/write electronics are in power-down mode.

Table 2: DC power requirements

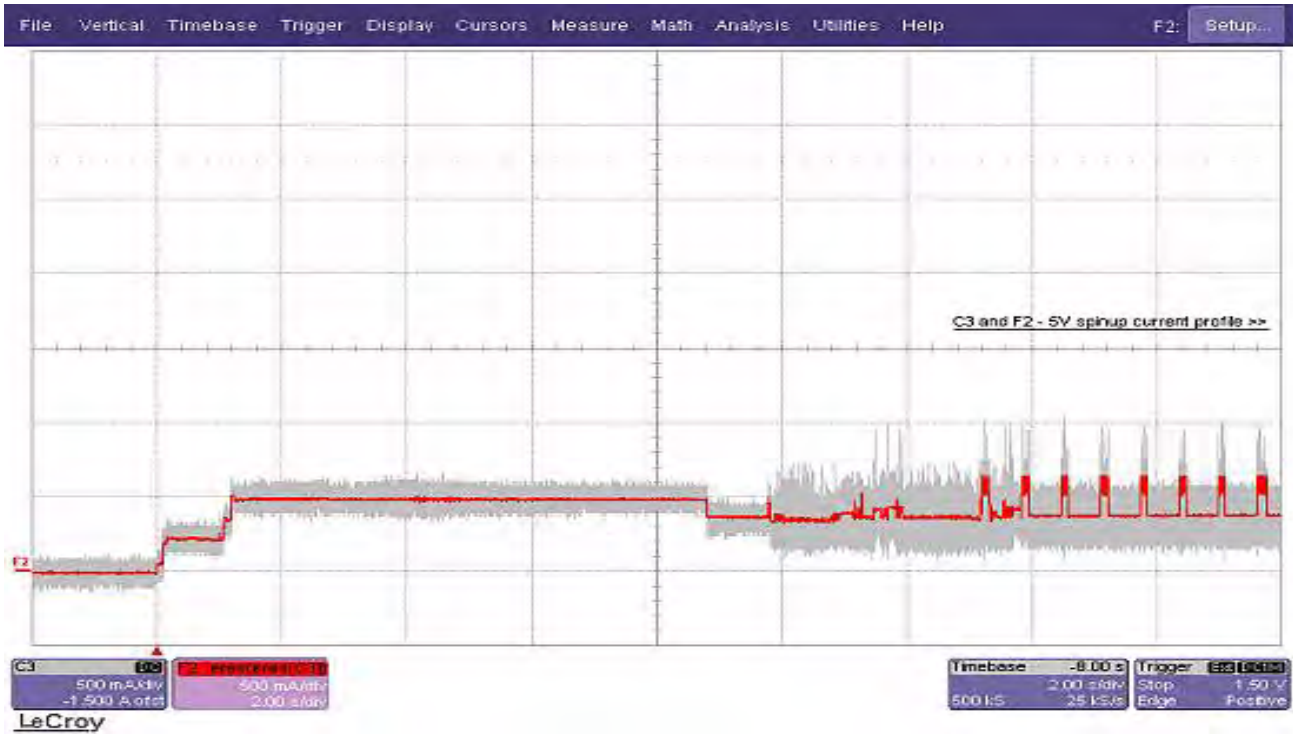
Power dissipation	Avg (watts 25° C)	Avg 5V typ amps	Avg 12V typ amps
Spinup	—	—	2.8 (peak)
Idle* †	6.39	0.27	0.42
Operating (average)	9.23	0.31	0.64
Standby	0.57	0.09	0.01
Sleep	0.57	0.09	0.01

*During periods of drive idle, some offline activity may occur according to the S.M.A.R.T. specification, which may increase acoustic and power to operational levels.

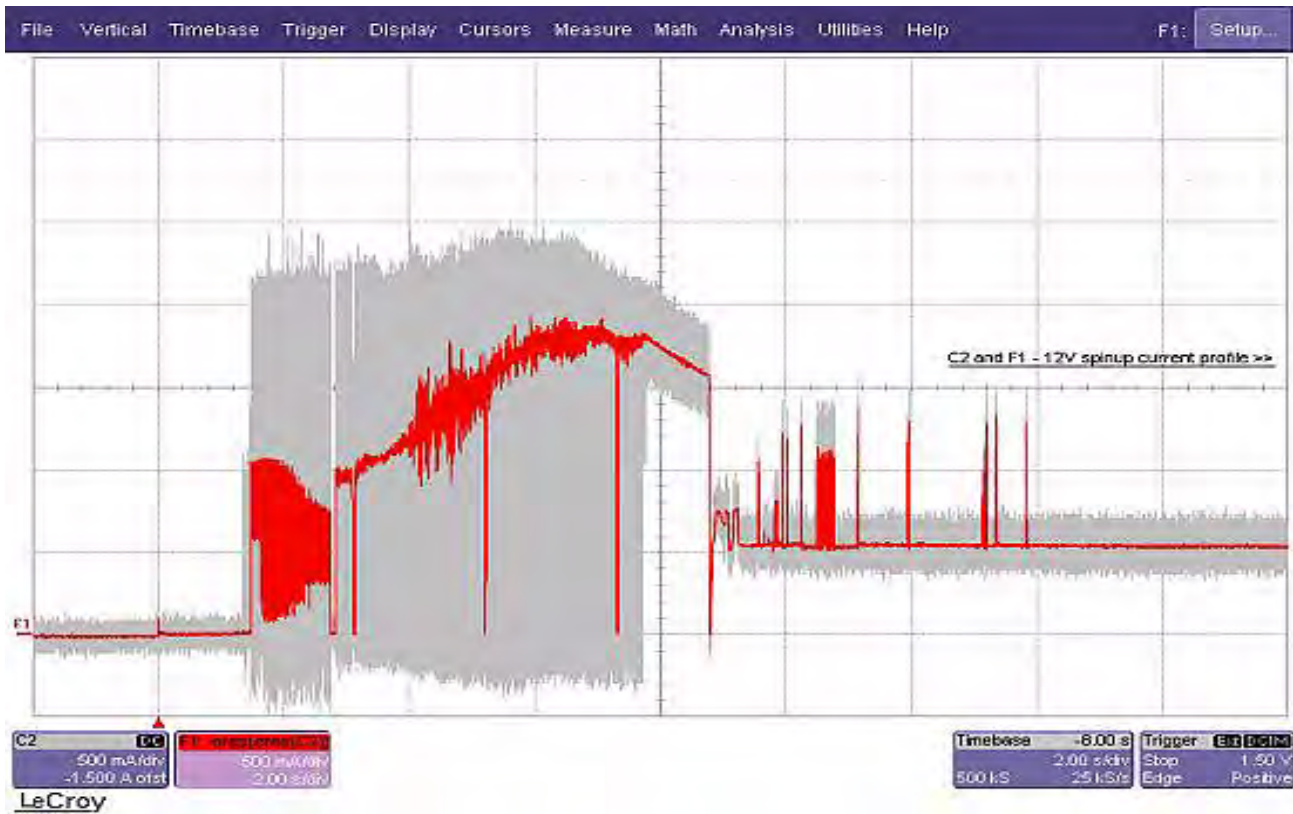
†5W IDLE with DIPLM Enabled

Note. Drive supports PHY layer power management. When enabled, a power savings of ~300mw can be achieved in idle, standby and sleep modes.

2.6.1.1 Typical current profiles



Note. Typical 5V startup and operation current profile



Note. Typical 12V startup and operation current profile

2.6.2 Conducted noise

Input noise ripple is measured at the host system power supply across an equivalent 80-ohm resistive load on the +12 volt line or an equivalent 15-ohm resistive load on the +5 volt line.

- Using 12-volt power, the drive is expected to operate with a maximum of 120 mV peak-to-peak square-wave injected noise at up to 10 MHz.
- Using 5-volt power, the drive is expected to operate with a maximum of 100 mV peak-to-peak square-wave injected noise at up to 10 MHz.

Note. Equivalent resistance is calculated by dividing the nominal voltage by the typical RMS read/write current.

2.6.3 Voltage tolerance

Voltage tolerance (including noise):

5V +10% / -10%
12V +10% / -10%

2.6.4 Power management modes

The drive provides programmable power management to provide greater energy efficiency. In most systems, you can control power management through the system setup program. The drive features the following power management modes:

Power modes	Heads	Spindle	Buffer
Active	Tracking	Rotating	Enabled
Idle	Tracking	Rotating	Enabled
Standby	Parked	Stopped	Enabled
Sleep	Parked	Stopped	Disabled

- **Active mode**

The drive is in active mode during the read/write and seek operations.

- **Idle mode**

The buffer remains enabled, and the drive accepts all commands and returns to active mode any time disk access is necessary.

- **Standby mode**

The drive enters standby mode when the host sends a standby Immediate command. If the host has set the standby timer, the drive can also enter standby mode automatically after the drive has been inactive for a specifiable length of time. The standby timer delay is established using a standby or idle command. In standby mode, the drive buffer is enabled, the heads are parked and the spindle is at rest. The drive accepts all commands and returns to active mode any time disk access is necessary.

- **Sleep mode**

The drive enters sleep mode after receiving a sleep command from the host. In sleep mode, the drive buffer is disabled, the heads are parked and the spindle is at rest. The drive leaves sleep mode after it receives a hard reset or soft reset from the host. After receiving a reset, the drive exits sleep mode and enters standby mode with all current translation parameters intact.

- **Idle and Standby timers**

Each time the drive performs an active function (read, write or seek), the standby timer is reinitialized and begins counting down from its specified delay times to zero. If the standby timer reaches zero before any drive activity is required, the drive makes a transition to standby mode. In both Idle and standby mode, the drive accepts all commands and returns to active mode when disk access is necessary.

2.7 Environmental specifications

2.7.1 Ambient temperature

Ambient temperature is defined as the temperature of the environment immediately surrounding the drive. Actual drive case temperature should not exceed 69°C (156°F) within the operating ambient conditions.

Operating:	0° to 60°C (32° to 140°F)
Nonoperating: *	-40° to 70°C (-40° to 158°F)

* See Section 2.10.1 for reliability projections.

2.7.2 Temperature gradient

Operating:	20°C per hour (68°F per hour max), without condensation
Nonoperating:	30°C per hour (86°F per hour max)

2.7.3 Humidity

2.7.3.1 Relative humidity

Operating:	5% to 95% noncondensing (30% per hour max)
Nonoperating:	5% to 95% noncondensing (30% per hour max)

2.7.3.2 Wet bulb temperature

Operating:	37.7°C (99.9°F max)
Nonoperating:	40°C (104°F max)

2.7.4 Altitude

Operating:	-60.96 m to 3,048 m (-200 ft. to 10,000+ ft.)
Nonoperating:	-60.96 m to 12,192 m (-200 ft. to 40,000+ ft.)

2.7.5 Shock

All shock specifications assume that the drive is mounted securely with the input shock applied at the drive mounting screws. Shock may be applied in the X, Y or Z axis.

2.7.5.1 Operating shock

These drives comply with the performance levels specified in this document when subjected to a maximum operating shock of 63Gs based on half-sine shock pulses of 2 msec during read operations. Shocks should not be repeated more than two times per second.

2.7.5.2 Nonoperating shock

The nonoperating shock level that the drive can experience without incurring physical damage or degradation in performance when subsequently put into operation is 300 Gs based on a nonrepetitive half-sine shock pulse of 2 msec duration.

2.7.6 Vibration

All vibration specifications assume that the drive is mounted securely with the input vibration applied at the drive mounting screws. Vibration may be applied in the X, Y or Z axis.

2.7.6.1 Operating vibration

The maximum vibration levels that the drive may experience while meeting the performance standards specified in this document are specified below.

5–350 Hz	0.50 Gs
350–500 Hz	0.25 Gs

2.7.6.2 Nonoperating vibration

The maximum nonoperating vibration levels that the drive may experience without incurring physical damage or degradation in performance when subsequently put into operation are specified below.

5–350 Hz	5.0 Gs
350–500 Hz	2.0 Gs

2.8 Acoustics

Drive acoustics are measured as overall A-weighted acoustic sound power levels (no pure tones). All measurements are consistent with ISO document 7779. Sound power measurements are taken under essentially free-field conditions over a reflecting plane. For all tests, the drive is oriented with the cover facing upward.

Note. For seek mode tests, the drive is placed in seek mode only. The number of seeks per second is defined by the following equation:

$$(\text{Number of seeks per second} = 0.4 / (\text{average latency} + \text{average access time}))$$

Table 3: Drive A-weighted Sound Power Levels (SWL, BA)

	Idle ^[1]	Performance Seek
2000GB model	2.7 bels (typ) 2.9 bels (max)	2.9 bels (typ) 3.3 bels (max)

[1] During periods of drive idle, some offline activity may occur according to the S.M.A.R.T. specification, which may increase acoustic and power to operational levels.

2.8.1 Test for Prominent Discrete Tones (PDTs)

Seagate follows the ECMA-74 standards for measurement and identification of PDTs. An exception to this process is the use of the absolute threshold of hearing. Seagate uses this threshold curve (originated in ISO 389-7) to discern tone audibility and to compensate for the inaudible components of sound prior to computation of tone ratios according to Annex D of the ECMA-74 standards.

2.9 Electromagnetic immunity

When properly installed in a representative host system, the drive operates without errors or degradation in performance when subjected to the radio frequency (RF) environments defined in the following table:

Table 4: Radio frequency environments

Test	Description	Performance level	Reference standard
Electrostatic discharge	Contact, HCP, VCP: ± 4 kV; Air: ± 8 kV	B	EN 61000-4-2: 95
Radiated RF immunity	80 to 1,000 MHz, 3 V/m, 80% AM with 1 kHz sine 900 MHz, 3 V/m, 50% pulse modulation @ 200 Hz	A	EN 61000-4-3: 96 ENV 50204: 95
Electrical fast transient	± 1 kV on AC mains, ± 0.5 kV on external I/O	B	EN 61000-4-4: 95
Surge immunity	± 1 kV differential, ± 2 kV common, AC mains	B	EN 61000-4-5: 95
Conducted RF immunity	150 kHz to 80 MHz, 3 Vrms, 80% AM with 1 kHz sine	A	EN 61000-4-6: 97
Voltage dips, interrupts	0% open, 5 seconds 0% short, 5 seconds 40%, 0.10 seconds 70%, 0.01 seconds	C C C B	EN 61000-4-11: 94

2.10 Reliability

2.10.1 Annualized Failure Rate (AFR) and Mean Time Between Failures (MTBF)

The product shall achieve an Annualized Failure Rate (AFR) of 0.34% (MTBF of 0.75 million hours) when operated in an environment of ambient air temperatures of 25°C. Operation at temperatures outside the specifications in Section 2.7 may increase the product AFR (decrease MTBF). AFR and MTBF are population statistics that are not relevant to individual units.

AFR and MTBF specifications are based on the following assumptions for desktop personal computer environments:

- 2,400 power-on-hours per year.
- 10,000 average motor start/stop cycles per year.
- Operations at nominal voltages.
- Temperatures outside the specifications in Section 2.7 may reduce the product reliability.
- Normal I/O duty cycle for desktop personal computers. Operation at excessive I/O duty cycle may degrade product reliability.

The desktop personal computer environment of power-on-hours, temperature, and I/O duty cycle affect the product AFR and MTBF. The AFR and MTBF will be degraded if used in an enterprise application

Nonrecoverable read errors	1 per 10 ¹⁴ bits read, max
Annualized Failure Rate (AFR)	0.34% (nominal power, 25°C ambient temperature)
LuL	300,000 cycles
Warranty	To determine the warranty for a specific drive, use a web browser to access the following web page: support.seagate.com/customer/warranty_validation.jsp From this page, click on the "Verify Your Warranty" link. You will be asked to provide the drive serial number, model number (or part number) and country of purchase. The system will display the warranty information for your drive.
Preventive maintenance	None required.

2.11 Agency certification

2.11.1 Safety certification

These products are certified to meet the requirements of UL60950-1, CSA60950-1 and EN60950 and so marked as to the certify agency.

2.11.2 Electromagnetic Compatibility (EMC)

Hard drives that display the CE mark comply with the European Union (EU) requirements specified in the Electromagnetic Compatibility Directive (2004/108/EC) as put into place 20 July 2007. Testing is performed to the levels specified by the product standards for Information Technology Equipment (ITE). Emission levels are defined by EN 55022, Class B and the immunity levels are defined by EN 55024.

Drives are tested in representative end-user systems. Although CE-marked Seagate drives comply with the directives when used in the test systems, we cannot guarantee that all systems will comply with the directives. The drive is designed for operation inside a properly designed enclosure, with properly shielded I/O cable (if necessary) and terminators on all unused I/O ports. Computer manufacturers and system integrators should confirm EMC compliance and provide CE marking for their products.

Korean RRL

If these drives have the Korean Communications Commission (KCC) logo, they comply with paragraph 1 of Article 11 of the Electromagnetic Compatibility control Regulation and meet the Electromagnetic Compatibility (EMC) Framework requirements of the Radio Research Laboratory (RRL) Communications Commission, Republic of Korea.

These drives have been tested and comply with the Electromagnetic Interference/Electromagnetic Susceptibility (EMI/EMS) for Class B products. Drives are tested in a representative, end-user system by a Korean-recognized lab.

- Family name: Barracuda XT Series
- Certificate number: In process

Australian C-Tick (N176)

If these models have the C-Tick marking, they comply with the Australia/New Zealand Standard AS/NZ CISPR22 and meet the Electromagnetic Compatibility (EMC) Framework requirements of the Australian Communication Authority (ACA).

2.11.3 FCC verification

These drives are intended to be contained solely within a personal computer or similar enclosure (not attached as an external device). As such, each drive is considered to be a subassembly even when it is individually marketed to the customer. As a subassembly, no Federal Communications Commission verification or certification of the device is required.

Seagate has tested this device in enclosures as described above to ensure that the total assembly (enclosure, disk drive, motherboard, power supply, etc.) does comply with the limits for a Class B computing device, pursuant to Subpart J, Part 15 of the FCC rules. Operation with noncertified assemblies is likely to result in interference to radio and television reception.

Radio and television interference. This equipment generates and uses radio frequency energy and if not installed and used in strict accordance with the manufacturer's instructions, may cause interference to radio and television reception.

This equipment is designed to provide reasonable protection against such interference in a residential installation. However, there is no guarantee that interference will not occur in a particular installation. If this equipment does cause interference to radio or television, which can be determined by turning the equipment on and off, you are encouraged to try one or more of the following corrective measures:

- Reorient the receiving antenna.
- Move the device to one side or the other of the radio or TV.
- Move the device farther away from the radio or TV.
- Plug the computer into a different outlet so that the receiver and computer are on different branch outlets.

If necessary, you should consult your dealer or an experienced radio/television technician for additional suggestions. You may find helpful the following booklet prepared by the Federal Communications Commission: *How to Identify and Resolve Radio-Television Interference Problems*. This booklet is available from the Superintendent of Documents, U.S. Government Printing Office, Washington, DC 20402. Refer to publication number 004-000-00345-4.

2.12 Environmental protection

Seagate designs its products to meet environmental protection requirements worldwide, including regulations restricting certain chemical substances.

2.12.1 European Union Restriction of Hazardous Substances (RoHS) Directive

The European Union Restriction of Hazardous Substances (RoHS) Directive, restricts the presence of chemical substances, including Lead, Cadmium, Mercury, Hexavalent Chromium, PBB and PBDE, in electronic products, effective July 2006. This drive is manufactured with components and materials that comply with the RoHS Directive.

2.12.2 China Restriction of Hazardous Substances (RoHS) Directive 中国限制危险物品的指令

This product has an Environmental Protection Use Period (EPUP) of 20 years. The following table contains information mandated by China's "Marking Requirements for Control of Pollution Caused by Electronic Information Products" Standard.



该产品具有20年的环境保护使用周期（EPUP）。下表包含了中国“电子产品所导致的污染的控制的记号要求”所指定的信息。

Name of Parts 部件名称	Toxic or Hazardous Substances or Elements有毒有害物质或元素					
	Lead 铅 (Pb)	Mercury 汞 (Hg)	Cadmium 镉 (Cd)	Hexavalent Chromium 六价铬 (Cr6+)	Polybrominated Diphenyl 多溴联苯 (PBB)	Polybrominated Diphenyl Ether 多溴二苯醚 (PBDE)
PCBA	X	O	O	O	O	O
HDA	X	O	O	O	O	O

"O" indicates the hazardous and toxic substance content of the part (at the homogenous material level) is lower than the threshold defined by the China RoHS MCV Standard.

“O”表示该部件（于同类物品程度上）所含的危险和有毒物质低于中国RoHS MCV标准所定义的阈值。

"X" indicates the hazardous and toxic substance content of the part (at the homogenous material level) is over the threshold defined by the China RoHS MCV Standard.

“X”表示该部件（于同类物品程度上）所含的危险和有毒物质超出中国RoHS MCV标准所定义的阈值。

2.13 Corrosive environment

Seagate electronic drive components pass accelerated corrosion testing equivalent to 10 years exposure to light industrial environments containing sulfurous gases, chlorine and nitric oxide, classes G and H per ASTM B845. However, this accelerated testing cannot duplicate every potential application environment. Users should use caution exposing any electronic components to uncontrolled chemical pollutants and corrosive chemicals as electronic drive component reliability can be affected by the installation environment. The silver, copper, nickel and gold films used in Seagate products are especially sensitive to the presence of sulfide, chloride, and nitrate contaminants. Sulfur is found to be the most damaging. In addition, electronic components should never be exposed to condensing water on the surface of the printed circuit board assembly (PCBA) or exposed to an ambient relative humidity greater than 95%. Materials used in cabinet fabrication, such as vulcanized rubber, that can outgas corrosive compounds should be minimized or eliminated. The useful life of any electronic equipment may be extended by replacing materials near circuitry with sulfide-free alternatives.

3.0 Configuring and mounting the drive

This section contains the specifications and instructions for configuring and mounting the drive.

3.1 Handling and static-discharge precautions

After unpacking, and before installation, the drive may be exposed to potential handling and electrostatic discharge (ESD) hazards. Observe the following standard handling and static-discharge precautions:

Caution:

- Before handling the drive, put on a grounded wrist strap, or ground yourself frequently by touching the metal chassis of a computer that is plugged into a grounded outlet. Wear a grounded wrist strap throughout the entire installation procedure.
- Handle the drive by its edges or frame *only*.
- The drive is extremely fragile—handle it with care. Do not press down on the drive top cover.
- Always rest the drive on a padded, antistatic surface until you mount it in the computer.
- Do not touch the connector pins or the printed circuit board.
- Do not remove the factory-installed labels from the drive or cover them with additional labels. Removal voids the warranty. Some factory-installed labels contain information needed to service the drive. Other labels are used to seal out dirt and contamination.

3.2 Configuring the drive

Each drive on the Serial ATA interface connects point-to-point with the Serial ATA host adapter. There is no master/slave relationship because each drive is considered a master in a point-to-point relationship. If two drives are attached on one Serial ATA host adapter, the host operating system views the two devices as if they were both “masters” on two separate ports. Both drives behave as if they are Device 0 (master) devices.

Serial ATA drives are designed for easy installation. It is usually not necessary to set any jumpers on the drive for proper operation; however, if you connect the drive and receive a “drive not detected” error, your SATA-equipped motherboard or host adapter may use a chipset that does not support SATA speed autonegotiation. If you have a motherboard or host adapter that does not support autonegotiation:

3.3 Serial ATA cables and connectors

The Serial ATA interface cable consists of four conductors in two differential pairs, plus three ground connections. The cable size may be 30 to 26 AWG with a maximum length of one meter (39.37 inches). See Table 5 for connector pin definitions. Either end of the SATA signal cable can be attached to the drive or host.

For direct backplane connection, the drive connectors are inserted directly into the host receptacle. The drive and the host receptacle incorporate features that enable the direct connection to be hot pluggable and blind mateable.

For installations which require cables, you can connect the drive as illustrated in Figure 1.

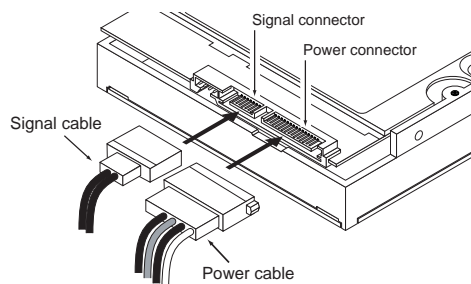


Figure 1. Attaching SATA cabling

Each cable is keyed to ensure correct orientation. Barracuda XT Series SATA drives support latching SATA connectors.

3.4 Drive mounting

You can mount the drive in any orientation using four screws in the side-mounting holes or four screws in the bottom-mounting holes. See Figure 2 for drive mounting dimensions. Follow these important mounting precautions when mounting the drive:

- Allow a minimum clearance of 0.030 inches (0.76 mm) around the entire perimeter of the drive for cooling.
- Use only 6-32 UNC mounting screws.
- The screws should be inserted no more than 0.150 inch (3.81 mm) into the bottom or side mounting holes.
- Do not overtighten the mounting screws (maximum torque: 6 inch-lb).

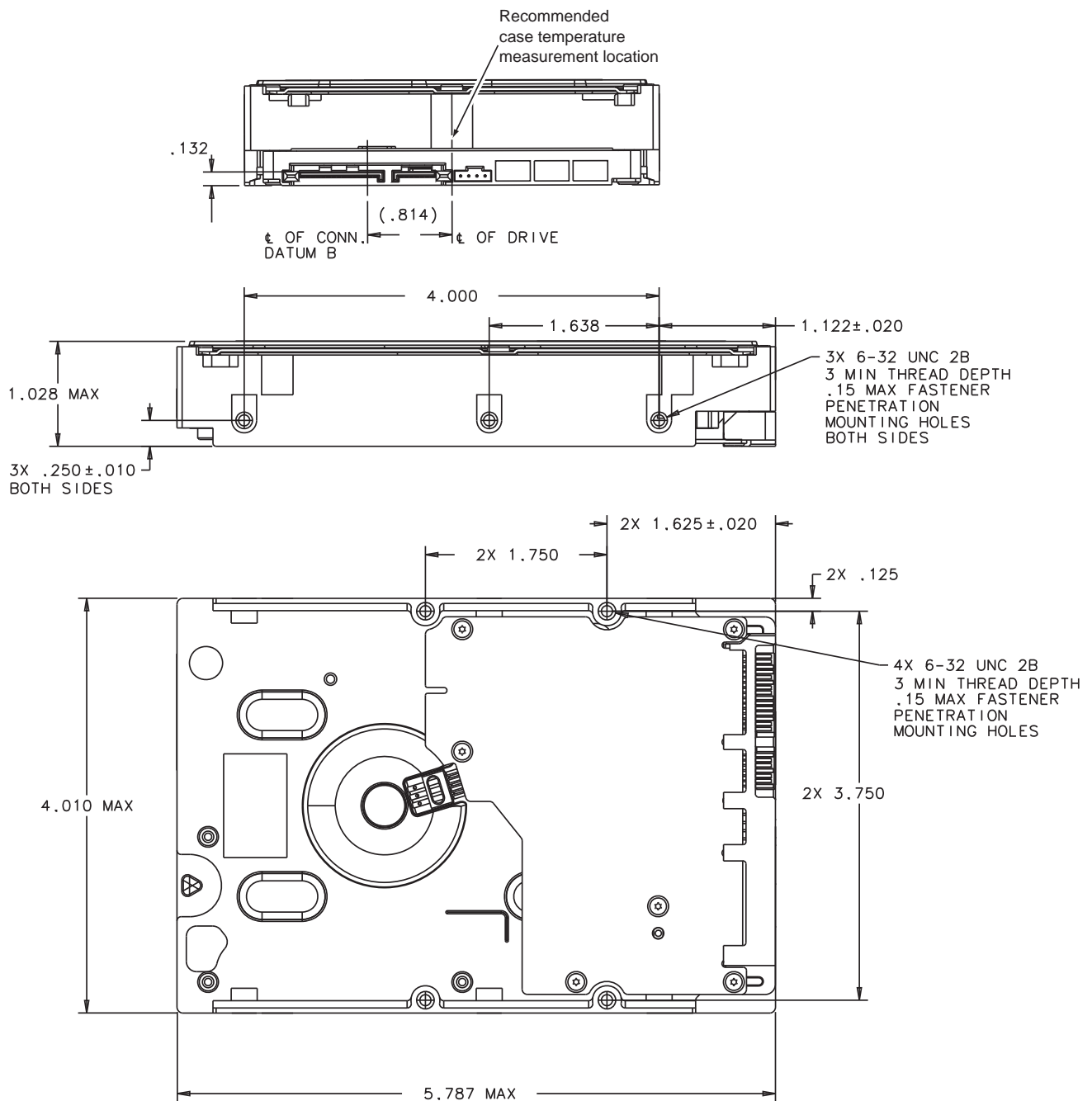


Figure 2. Mounting dimensions (2000GB model)

4.0 Serial ATA (SATA) interface

These drives use the industry-standard Serial ATA interface that supports FIS data transfers. It supports ATA programmed input/output (PIO) modes 0–4; multiword DMA modes 0–2, and Ultra DMA modes 0–6.

For detailed information about the Serial ATA interface, refer to the “Serial ATA: High Speed Serialized AT Attachment” specification.

4.1 Hot-Plug compatibility

Barracuda XT Series SATA drives incorporate connectors which enable you to hot plug these drives in accordance with the Serial ATA Revision 2.6 specification. This specification can be downloaded from www.serialata.org.

4.2 Serial ATA device plug connector pin definitions

Table 5 summarizes the signals on the Serial ATA interface and power connectors.

Table 5: Serial ATA connector pin definitions

Segment	Pin	Function	Definition
Signal	S1	Ground	2nd mate
	S2	A+	Differential signal pair A from Phy
	S3	A-	
	S4	Ground	2nd mate
	S5	B-	Differential signal pair B from Phy
	S6	B+	
	S7	Ground	2nd mate

Key and spacing separate signal and power segments

Power	P1	V ₃₃	3.3V power
	P2	V ₃₃	3.3V power
	P3	V ₃₃	3.3V power, pre-charge, 2nd mate
	P4	Ground	1st mate
	P5	Ground	2nd mate
	P6	Ground	2nd mate
	P7	V ₅	5V power, pre-charge, 2nd mate
	P8	V ₅	5V power
	P9	V ₅	5V power
	P10	Ground	2nd mate
	P11	Ground or LED signal	If grounded, drive does not use deferred spin
	P12	Ground	1st mate.
	P13	V ₁₂	12V power, pre-charge, 2nd mate
	P14	V ₁₂	12V power
	P15	V ₁₂	12V power

Notes:

- All pins are in a single row, with a 1.27 mm (0.050") pitch.
- The comments on the mating sequence apply to the case of backplane blindmate connector only. In this case, the mating sequences are:
 - the ground pins P4 and P12.
 - the pre-charge power pins and the other ground pins.
 - the signal pins and the rest of the power pins.
- There are three power pins for each voltage. One pin from each voltage is used for pre-charge when installed in a blind-mate backplane configuration.
- All used voltage pins (V_x) must be terminated.

4.3 Supported ATA commands

The following table lists Serial ATA standard commands that the drive supports.

For a detailed description of the ATA commands, refer to the Serial ATA International Organization: Serial ATA Revision 2.6 (<http://www.sata-io.org>).

See “S.M.A.R.T. commands” on page 28 for details and subcommands used in the S.M.A.R.T. implementation.

Table 6: Supported ATA commands

Command name	Command code (in hex)
Check Power Mode	E5 _H
Device Configuration Freeze Lock	B1 _H / C1 _H
Device Configuration Identify	B1 _H / C2 _H
Device Configuration Restore	B1 _H / C0 _H
Device Configuration Set	B1 _H / C3 _H
Device Reset	08 _H
Download Microcode	92 _H
Execute Device Diagnostics	90 _H
Flush Cache	E7 _H
Flush Cache Extended	EA _H
Format Track	50 _H
Identify Device	EC _H
Idle	E3 _H
Idle Immediate	E1 _H
Initialize Device Parameters	91 _H
Read Buffer	E4 _H
Read DMA	C8 _H
Read DMA Extended	25 _H
Read DMA Without Retries	C9 _H
Read Log Ext	2F _H
Read Multiple	C4 _H
Read Multiple Extended	29 _H
Read Native Max Address	F8 _H
Read Native Max Address Extended	27 _H
Read Sectors	20 _H
Read Sectors Extended	24 _H
Read Sectors Without Retries	21 _H
Read Verify Sectors	40 _H
Read Verify Sectors Extended	42 _H
Read Verify Sectors Without Retries	41 _H
Recalibrate	10 _H
Security Disable Password	F6 _H

Command name	Command code (in hex)
Security Erase Prepare	F3 _H
Security Erase Unit	F4 _H
Security Freeze	F5 _H
Security Set Password	F1 _H
Security Unlock	F2 _H
Seek	70 _H
Set Features	EF _H
Set Max Address Note: Individual Set Max Address commands are identified by the value placed in the Set Max Features register as defined to the right.	F9 _H Address: 00 _H Password: 01 _H Lock: 02 _H Unlock: 03 _H Freeze Lock: 04 _H
Set Max Address Extended	37 _H
Set Multiple Mode	C6 _H
Sleep	E6 _H
S.M.A.R.T. Disable Operations	B0 _H / D9 _H
S.M.A.R.T. Enable/Disable Autosave	B0 _H / D2 _H
S.M.A.R.T. Enable Operations	B0 _H / D8 _H
S.M.A.R.T. Execute Offline	B0 _H / D4 _H
S.M.A.R.T. Read Attribute Thresholds	B0 _H / D1 _H
S.M.A.R.T. Read Data	B0 _H / D0 _H
S.M.A.R.T. Read Log Sector	B0 _H / D5 _H
S.M.A.R.T. Return Status	B0 _H / DA _H
S.M.A.R.T. Save Attribute Values	B0 _H / D3 _H
S.M.A.R.T. Write Log Sector	B0 _H / D6 _H
Standby	E2 _H
Standby Immediate	E0 _H
Write Buffer	E8 _H
Write DMA	CA _H
Write DMA Extended	35 _H
Write DMA FUA Extended	3D _H
Write DMA Without Retries	CB _H
Write Log Extended	3F _H
Write Multiple	C5 _H
Write Multiple Extended	39 _H
Write Multiple FUA Extended	CE _H
Write Sectors	30 _H
Write Sectors Without Retries	31 _H
Write Sectors Extended	34 _H
Write Uncorrectable	45 _H

4.3.1 Identify Device command

The Identify Device command (command code EC_H) transfers information about the drive to the host following power up. The data is organized as a single 512-byte block of data, whose contents are shown in Table 6 on page 21. All reserved bits or words should be set to zero. Parameters listed with an “x” are drive-specific or vary with the state of the drive. See Section 2.0 on page 3 for default parameter settings.

The following commands contain drive-specific features that may not be included in the Serial ATA specification.

Word	Description	Value
0	Configuration information: <ul style="list-style-type: none"> • Bit 15: 0 = ATA; 1 = ATAPI • Bit 7: removable media • Bit 6: removable controller • Bit 0: reserved 	0C5A _H
1	Number of logical cylinders	16,383
2	ATA-reserved	0000 _H
3	Number of logical heads	16
4	Retired	0000 _H
5	Retired	0000 _H
6	Number of logical sectors per logical track: 63	003F _H
7–9	Retired	0000 _H
10–19	Serial number: (20 ASCII characters, 0000 _H = none)	ASCII
20	Retired	0000 _H
21	Retired	0400 _H
22	Obsolete	0000 _H
23–26	Firmware revision (8 ASCII character string, padded with blanks to end of string)	x.xx
27–46	Drive model number: (40 ASCII characters, padded with blanks to end of string)	
47	(Bits 7–0) Maximum sectors per interrupt on Read multiple and Write multiple (16)	8010 _H
48	Reserved	0000 _H
49	Standard Standby timer, IORDY supported and may be disabled	2F00 _H
50	ATA-reserved	0000 _H
51	PIO data-transfer cycle timing mode	0200 _H
52	Retired	0200 _H
53	Words 54–58, 64–70 and 88 are valid	0007 _H
54	Number of current logical cylinders	xxxx _H
55	Number of current logical heads	xxxx _H
56	Number of current logical sectors per logical track	xxxx _H
57–58	Current capacity in sectors	xxxx _H
59	Number of sectors transferred during a Read Multiple or Write Multiple command	xxxx _H

Word	Description	Value
60–61	Total number of user-addressable LBA sectors available (see Section 2.1 for related information) *Note: The maximum value allowed in this field is: 0FFFFFFFh (268,435,455 sectors, 137 Gbytes). Drives with capacities over 137 Gbytes will have 0FFFFFFFh in this field and the actual number of user-addressable LBAs specified in words 100-103. This is required for drives that support the 48-bit addressing feature.	0FFFFFFFh*
62	Retired	0000 _H
63	Multiword DMA active and modes supported (see note following this table)	xx07 _H
64	Advanced PIO modes supported (modes 3 and 4 supported)	0003 _H
65	Minimum multiword DMA transfer cycle time per word (120 nsec)	0078 _H
66	Recommended multiword DMA transfer cycle time per word (120 nsec)	0078 _H
67	Minimum PIO cycle time without IORDY flow control (240 nsec)	00F0 _H
68	Minimum PIO cycle time with IORDY flow control (120 nsec)	0078 _H
69–74	ATA-reserved	0000 _H
75	Queue depth	001F _H
76	Serial ATA capabilities	xxxx _H
77	Reserved for future Serial ATA definition	xxxx _H
78	Serial ATA features supported	xxxx _H
79	Serial ATA features enabled	xxxx _H
80	Major version number	003E _H
81	Minor version number	0028 _H
82	Command sets supported	364B _H
83	Command sets supported	7C03 _H
84	Command sets support extension (see note following this table)	4003 _H See Word 108-111 note. (4003H = 0100000000000011 binary)
85	Command sets enabled	30xx _H
86	Command sets enabled	0001 _H
87	Command sets enable extension	4000 _H
88	Ultra DMA support and current mode (see note following this table)	xx3F _H
89	Security erase time	0000 _H
90	Enhanced security erase time	0000 _H
92	Master password revision code	FFFE _H
93	Hardware reset value	xxxx _H
95–99	ATA-reserved	0000 _H
100–103	Total number of user-addressable LBA sectors available (see Section 2.1 for related information). These words are required for drives that support the 48-bit addressing feature. Maximum value: 0000FFFFFFFFFh.	ST32000641AS = 3,907,029,168
104–107	ATA-reserved	0000 _H

Word	Description	Value
108–111	The mandatory value of the world wide name (WWN) for the drive. NOTE: This field is valid if word 84, bit 8 is set to 1 indicating 64-bit WWN support.	Each drive will have a unique value.
112–127	ATA-reserved	0000 _H
128	Security status	0001 _H
129–159	Seagate-reserved	xxxx _H
160–254	ATA-reserved	0000 _H
255	Integrity word	xxA5 _H

Note. Advanced Power Management (APM) and Automatic Acoustic Management (AAM) features are not supported

Note. See the bit descriptions below for words 63, 84, and 88 of the Identify Drive data.

Description (if bit is set to 1)		
Bit	Word 63	
0	Multiword DMA mode 0 is supported.	
1	Multiword DMA mode 1 is supported.	
2	Multiword DMA mode 2 is supported.	
8	Multiword DMA mode 0 is currently active.	
9	Multiword DMA mode 1 is currently active.	
10	Multiword DMA mode 2 is currently active.	
Bit	Word 84	
0	SMART error login is supported.	
1	SMART self-test is supported.	
2	Media serial number is supported.	
3	Media Card Pass Through Command feature set is supported.	
4	Streaming feature set is supported.	
5	GPL feature set is supported.	
6	WRITE DMA FUA EXT and WRITE MULTIPLE FUA EXT commands are supported.	
7	WRITE DMA QUEUED FUA EXT command is supported.	
8	64-bit World Wide Name is supported.	
9-10	Obsolete.	
11-12	Reserved for TLC.	
13	IDLE IMMEDIATE command with IUNLOAD feature is supported.	
14	Shall be set to 1.	
15	Shall be cleared to 0.	
Bit	Word 88	
0	Ultra DMA mode 0 is supported.	
1	Ultra DMA mode 1 is supported.	

	2	Ultra DMA mode 2 is supported.
	3	Ultra DMA mode 3 is supported.
	4	Ultra DMA mode 4 is supported.
	5	Ultra DMA mode 5 is supported.
	6	Ultra DMA mode 6 is supported.
	8	Ultra DMA mode 0 is currently active.
	9	Ultra DMA mode 1 is currently active.
	10	Ultra DMA mode 2 is currently active.
	11	Ultra DMA mode 3 is currently active.
	12	Ultra DMA mode 4 is currently active.
	13	Ultra DMA mode 5 is currently active.
	14	Ultra DMA mode 6 is currently active.

4.3.2 Set Features command

This command controls the implementation of various features that the drive supports. When the drive receives this command, it sets BSY, checks the contents of the Features register, clears BSY and generates an interrupt. If the value in the register does not represent a feature that the drive supports, the command is aborted. Power-on default has the read look-ahead and write caching features enabled. The acceptable values for the Features register are defined as follows:

Table 7: Set Features command values

02 _H	Enable write cache (<i>default</i>).
03 _H	Set transfer mode (based on value in Sector Count register). Sector Count register values:
00 _H	Set PIO mode to default (PIO mode 2).
01 _H	Set PIO mode to default and disable IORDY (PIO mode 2).
08 _H	PIO mode 0
09 _H	PIO mode 1
0A _H	PIO mode 2
0B _H	PIO mode 3
0C _H	PIO mode 4 (<i>default</i>)
20 _H	Multiword DMA mode 0
21 _H	Multiword DMA mode 1
22 _H	Multiword DMA mode 2
40 _H	Ultra DMA mode 0
41 _H	Ultra DMA mode 1
42 _H	Ultra DMA mode 2
43 _H	Ultra DMA mode 3
44 _H	Ultra DMA mode 4
45 _H	Ultra DMA mode 5
46 _H	Ultra DMA mode 6
10 _H	Enable use of SATA features
55 _H	Disable read look-ahead (read cache) feature.
82 _H	Disable write cache
90 _H	Disable use of SATA features
AA _H	Enable read look-ahead (read cache) feature (<i>default</i>).
F1 _H	Report full capacity available

Note. At power-on, or after a hardware or software reset, the default values of the features are as indicated above.

4.3.3 S.M.A.R.T. commands

S.M.A.R.T. provides near-term failure prediction for disk drives. When S.M.A.R.T. is enabled, the drive monitors predetermined drive attributes that are susceptible to degradation over time. If self-monitoring determines that a failure is likely, S.M.A.R.T. makes a status report available to the host. Not all failures are predictable. S.M.A.R.T. predictability is limited to the attributes the drive can monitor. For more information on S.M.A.R.T. commands and implementation, see the *Draft ATA-5 Standard*.

SeaTools diagnostic software activates a built-in drive self-test (DST S.M.A.R.T. command for D4_H) that eliminates unnecessary drive returns. The diagnostic software ships with all new drives and is also available at: <http://seatools.seagate.com>.

This drive is shipped with S.M.A.R.T. features disabled. You must have a recent BIOS or software package that supports S.M.A.R.T. to enable this feature. The table below shows the S.M.A.R.T. command codes that the drive uses.

Table 8: S.M.A.R.T. commands

Code in features register	S.M.A.R.T. command
D0 _H	S.M.A.R.T. Read Data
D2 _H	S.M.A.R.T. Enable/Disable Attribute Autosave
D3 _H	S.M.A.R.T. Save Attribute Values
D4 _H	S.M.A.R.T. Execute Off-line Immediate (runs DST)
D5 _H	S.M.A.R.T. Read Log Sector
D6 _H	S.M.A.R.T. Write Log Sector
D8 _H	S.M.A.R.T. Enable Operations
D9 _H	S.M.A.R.T. Disable Operations
DA _H	S.M.A.R.T. Return Status

Note. If an appropriate code is not written to the Features Register, the command is aborted and 0x04 (abort) is written to the Error register.

5.0 Seagate Technology support services

Internet

For information regarding Seagate products and services, visit www.seagate.com.

Worldwide support is available 24 hours daily by e-mail for your questions.

Presales Support:

Presales@Seagate.com

Technical Support:

DiscSupport@Seagate.com

Warranty Support:

http://www.seagate.com/www/en-us/support/warranty_&_returns_assistance

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Customer Service Operations

Warranty Service

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Data Recovery Services

Seagate offers data recovery services for all formats and all brands of storage media. Our data recovery services labs are currently located throughout the world. Additional information, including an online request form and data loss prevention resources, is available at <http://services.seagate.com/index.aspx>.

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USA/Canada/Latin America support services

For an extensive list of telephone numbers to technical support, presales and warranty service in USA/Canada/Latin America, including business hours, go to the "Contact Us" page on www.seagate.com.

Global Customer Support

Presales, Technical, and Warranty Support

Call Center	Toll-free	Direct dial
USA, Canada, and Mexico	1-800-SEAGATE	+1-405-324-4700

Data Recovery Services

Call Center	Toll-free	Direct dial	FAX
USA, Canada, and Mexico	1-800-475-0143	+1-905-474-2162	1-800-475-0158 +1-905-474-2459

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Index

A

acceleration 11
acoustics 12
active mode 9
agency certification 13
altitude 10
ambient temperature 7, 10
Annualized Failure Rate (AFR) 13
areal density 5
ATA commands 21
Australia/New Zealand Standard AS/NZ CISPR22 14
Australian Communication Authority (ACA) 14
Australian C-Tick 14

B

buffer 6

C

cables and connectors 17
cache 6
capacity 5
case temperature 10
CE mark 13
certification 13
Check Power Mode 21
China RoHS directive 15
compatibility 13
conducted noise 9
conducted RF immunity 12
configuring and mounting the drive 16
connectors 17
corrosive environment 15
CSA60950-1 13
cylinders 5

D

data-transfer rates 1
DC power 7
default logical geometry 5
density 5
Device Configuration Freeze Lock 21
Device Configuration Identify 21
Device Configuration Restore 21
Device Configuration Set 21
Device Reset 21
dimensions 18
dissipation 7
Download Microcode 21
duty cycle 13

E

electrical fast transient 12
Electromagnetic Compatibility (EMC) 13, 14
Electromagnetic Compatibility control Regulation 14
Electromagnetic Compatibility Directive (2004/108/EC) 13
electromagnetic immunity 12
electrostatic discharge (ESD) 12, 16
EN 55022, Class B 13
EN 55024 13
EN60950 13
enclosures 14
environmental specifications 10
error-correction algorithms 1
errors 13
ESD 16
EU RoHS directive 15
European Union (EU) requirements 13
Execute Device Diagnostics 21

F

FCC verification 14
features 1
Flush Cache 21
Flush Cache Extended 21
Format Track 21
formatted capacity 5

G

geometry 5
Gs (acceleration of gravity) 11
guaranteed sectors 5

H

handling precautions 16
heads 5
height 6
humidity 10

I

I/O data-transfer rate 5
I/O duty cycle 13
Identify Device 21
Identify Device command 23
Idle 21
idle (DC power) 7
Idle Immediate 21
idle mode 7, 9
Information Technology Equipment (ITE) 13
Initialize Device Parameters 21
input noise ripple 9
input voltage 7
interface 5, 19

interference 14
internal data-transfer rate OD 5
ISO document 7779 12

K

Korean Communications Commission (KCC) 14
Korean Radio Research Laboratory (RRL) 14

L

LBA mode 5
length 6
logical geometry 5

M

maintenance 13
master/slave 2
Mean Time Between Failures (MTBF) 13
mounting 18

N

noise 9
nonoperating shock 11
nonoperating vibration 11
nonrecoverable read errors 13

O

operating (DC power) 7
operating power 7
operating shock 11
operating vibration 11

P

perpendicular recording technology 1
physical characteristics 6
point-to-point 2, 17
power consumption 7
power dissipation 7
power management modes 9
power modes 9
power specifications 7
power-on to ready 6
power-on-hours 13
precautions 16
printed circuit board 16
programmable power management 9
prominent discrete tone 12

Q

quick reference 3

R

Radiated RF immunity 12
radio and television interference 14
radio frequency (RF) 12
random seeks 7
Read Buffer 21
Read DMA 21
Read DMA Extended 21
Read DMA Without Retries 21
read errors 13
Read Log Ext 21
Read Multiple 21
Read Multiple Extended 21
Read Native Max Address 21
Read Native Max Address Extended 21
Read Sectors 21
Read Sectors Extended 21
Read Sectors Without Retries 21
Read Verify Sectors 21
Read Verify Sectors Extended 21
Read Verify Sectors Without Retries 21
read/write heads 5
read/write power 7
ready to spindle stop 6
Recalibrate 21
recording density 5
recording method 5
recording technology 5
relative humidity 10
reliability 13
RMS read/write current 9
RoHS 15
RRL 14

S

S.M.A.R.T. Disable Operations 22
S.M.A.R.T. Enable Operations 22
S.M.A.R.T. Enable/Disable Autosave 22
S.M.A.R.T. Execute Offline 22
S.M.A.R.T. implementation 21
S.M.A.R.T. Read Attribute Thresholds 22
S.M.A.R.T. Read Data 22
S.M.A.R.T. Read Log Sector 22
S.M.A.R.T. Return Status 22
S.M.A.R.T. Save Attribute Values 22
S.M.A.R.T. Write Log sector 22
safety certification 13
SATA ports 2
sectors 5
sectors per track 5
Security Disable Password 21
Security Erase Prepare 22
Security Erase Unit 22
Security Freeze 22

- Security Set Password 22
- Security Unlock 22
- Seek 22
- seek mode 7
- seek time 6
- Serial ATA (SATA) interface 19
- servo electronics 7
- Set Features 22
- Set Max Address 22
- Set Max Address Extended 22
- Set Multiple Mode 22
- shock 11
- Sleep 22
- sleep (DC power) 7
- sleep mode 9
- sound 12
- Specification summary table 3
- spindle speed 5
- spinup (DC power) 7
- spinup power 7
- Standby 22
- standby (DC power) 7
- Standby Immediate 22
- standby mode 7, 9
- standby timer 9
- standby to ready 6
- Start/stop times 6
- static-discharge 16
- subassembly 14
- support services 29
- surge immunity 12

T

- technical support services 29
- temperature 10
- temperature gradient 10
- timers (Idle and Standby) 9
- track density 5

U

- UL60950-1 13

V

- vibration 11
- voltage 7
- voltage dips, interrupts 12
- voltage tolerance 9

W

- warranty 13
- weight 6
- wet bulb temperature 10
- width 6

- Write Buffer 22
- Write DMA 22
- Write DMA Extended 22
- Write DMA FUA Extended 22
- Write DMA Without Retries 22
- Write Log Extended 22
- Write Multiple 22
- Write Multiple Extended 22
- Write Multiple FUA Extended 22
- Write Sectors 22
- Write Sectors Extended 22
- Write Sectors Without Retries 22
- Write Uncorrectable 22



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